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Control of Nonlinear and Hybrid Process Systems

Panagiotis D. Christofides, Nael El-Farra, 2005-10-04 This monograph provides insight and fundamental understanding into the feedback control of nonlinear and hybrid process systems. It presents state of the art methods for the synthesis of nonlinear feedback controllers for nonlinear and hybrid systems with uncertainty constraints and time delays with numerous applications especially to chemical processes. It covers both state feedback and output feedback including state estimator design controller designs. Control of Nonlinear and Hybrid Process Systems includes numerous comments and remarks providing insight and fundamental understanding into the feedback control of nonlinear and hybrid systems as well as applications that demonstrate the implementation and effectiveness of the presented control methods. The book includes many detailed examples which can be easily modified by a control engineer to be tailored to a specific application. This book is useful for researchers in control systems theory graduate students pursuing their degree in control systems and control engineers.

Identification of Nonlinear Systems Using Neural Networks and Polynomial Models Andrzej

Janczak, 2004-11-18 This monograph systematically presents the existing identification methods of nonlinear systems using the block oriented approach. It surveys various known approaches to the identification of Wiener and Hammerstein systems which are applicable to both neural network and polynomial models. The book gives a comparative study of their gradient approximation accuracy computational complexity and convergence rates and furthermore presents some new and original methods concerning the model parameter adjusting with gradient based techniques. Identification of Nonlinear Systems Using Neural Networks and Polynomial Models is useful for researchers engineers and graduate students in nonlinear systems and neural network theory.

Control Reconfiguration of Dynamical Systems Thomas Steffen, 2005-08-31

Reconfiguration an approach for fault tolerant control involves changing the control structure in response to the fault. This monograph extends this idea to actuator faults and studies in detail the so called virtual actuator approach. Control Reconfiguration of Dynamical Systems also introduces structural analysis as a tool for reconfiguration. Because a fault changes the structure of the system the reconfiguration solution is sought on a structural level. Novel algorithms are presented to test for reconfigurability and to find a reconfiguration solution. A MATLAB toolbox is supplied which contains the main algorithms and examples. The book addresses advanced engineering students developers and researchers that have a specific interest in control reconfiguration.

Control of Uncertain Systems: Modelling, Approximation, and Design Bruce A.

Francis, 2006-03-07 This Festschrift contains a collection of articles by friends co authors colleagues and former Ph D students of Keith Glover. Professor of Engineering at the University of Cambridge on the occasion of his sixtieth birthday. Professor Glover's scientific work spans a wide variety of topics the main themes being system identification model reduction and approximation robust controller synthesis and control of aircraft and engines. The articles in this volume are a tribute to

Professor Glover's seminal work in these areas **Internal and External Stabilization of Linear Systems with Constraints** Ali Saberi, Anton A. Stoorvogel, Peddapullaiah Sannuti, 2012-06-21 Unifying two decades of research this book is the first to establish a comprehensive foundation for a systematic analysis and design of linear systems with general state and input constraints For such systems which can be used as models for most nonlinear systems the issues of stability controller design additional constraints and satisfactory performance are addressed The book is an excellent reference for practicing engineers graduate students and researchers in control systems theory and design It may also serve as an advanced graduate text for a course or a seminar in nonlinear control systems theory and design in applied mathematics or engineering departments Minimal prerequisites include a first graduate course in state space methods as well as a first course in control systems design **German books in print**, 2002 *Control of Sandwich Nonlinear Systems* Avinash Taware, Gang Tao, 2003-03-18 V VII X Table of Contents Table of Contents XI XII Table of Contents A Taware and G Tao Control of Sandwich Nonlinear Systems LNCIS 288 pp 1 8 2003 Springer Verlag Berlin Heidelberg 2003 A Taware and G Tao Control of Sandwich Nonlinear Systems LNCIS 288 pp 9 16 2003 Springer Verlag Berlin Heidelberg 2003 x t pilot valve piston position Return Pressure Source Return Load M b y t A Taware and G Tao Control of Sandwich Nonlinear Systems LNCIS 288 pp 17 28 2003 Springer Verlag Berlin Heidelberg 2003 load displacement y t 3 2 1 0 1 2 3 0 10 20 30 40 50 60 70 80 90 100 solid without DZ dotted with DZ Load displacement y t 0 4 0 2 0 0 2 0 4 0 6 0 8 10 20 30 40 50 60 70 80 90 100 solid without DZ dotted with DZ dashdot compensated Load displacement y t 3 2 1 0 1 2 3 0 10 20 30 40 50 60 70 80 90 100 Control input x t 0 8 0 6 0 4 0 2 0 0 2 0 4 0 6 0 10 20 30 40 50 60 70 80 90 100 solid without DZ dotted with DZ dashdot compensated Load displacement y t 0 6 0 4 0 2 0 0 2 0 4 0 6 0 8 0 10 20 30 40 50 60 70 80 90 100 solid without DZ dotted with DZ dashdot compensated A Taware and G Tao Control of Sandwich Nonlinear Systems LNCIS 288 pp 29 54 2003 Springer Verlag Berlin Heidelberg 2003 Technical Abstract Bulletin Defense Documentation Center (U.S.), 1964

Bifurcation Control Guanrong Chen, David John Hill, Xinghuo Yu, 2003-08-26 Bifurcation control refers to the task of designing a controller that can modify the bifurcation properties of a given nonlinear system so as to achieve some desirable dynamical behaviors There exists no similar control theory oriented book available in the market that is devoted to the subject of bifurcation control written by control engineers for control engineers World renowned leading experts in the field provide their state of the art survey about the extensive research that has been done over the last few years in this subject The book is not only aimed at active researchers in the field of bifurcation control and its applications but also at a general audience in related fields *Adaptive Control Design and Analysis* Gang Tao, 2003-07-09 A systematic and unified presentation of the fundamentals of adaptive control theory in both continuous time and discrete time Today adaptive control theory has grown to be a rigorous and mature discipline As the advantages of adaptive systems for developing advanced applications grow apparent adaptive control is becoming more popular in many fields of engineering and science Using a

simple balanced and harmonious style this book provides a convenient introduction to the subject and improves one's understanding of adaptive control theory Adaptive Control Design and Analysis features Introduction to systems and control Stability operator norms and signal convergence Adaptive parameter estimation State feedback adaptive control designs Parametrization of state observers for adaptive control Unified continuous and discrete time adaptive control L1 a robustness theory for adaptive systems Direct and indirect adaptive control designs Benchmark comparison study of adaptive control designs Multivariate adaptive control Nonlinear adaptive control Adaptive compensation of actuator nonlinearities End of chapter discussion problems and advanced topics As either a textbook or reference this self contained tutorial of adaptive control design and analysis is ideal for practicing engineers researchers and graduate students alike Advanced Topics in Control Systems Theory Antonio Loría, Françoise Lamnabhi-Lagarrigue, Elena Panteley, 2006-02-09 This book includes selected contributions by lecturers at the third annual Formation d'Automatique de Paris It provides a well integrated synthesis of the latest thinking in nonlinear optimal control observer design stability analysis and structural properties of linear systems without the need for an exhaustive literature review The internationally known contributors to this volume represent many of the most reputable control centers in Europe **Control of Redundant Robot Manipulators** Rajni V. Patel, F. Shadpey, 2005-05-04 This monograph provides a comprehensive and thorough treatment of the problem of controlling a redundant robot manipulator It presents the latest research from the field with a good balance between theory and practice All theoretical developments are verified both via simulation and experimental work on an actual prototype redundant robot manipulator This book is the first text aimed at graduate students and researchers working in the area of redundant manipulators giving a comprehensive coverage of control of redundant robot manipulators from the viewpoint of theory and experimentation **Theory of the Non-linear Analog Phase Locked Loop** Nikolaos I. Margaris, 2004-05-18 This book develops for the first time a complete and connected nonlinear theory for the analog Phase Locked Loop PLL which clarifies the obscure points of its complex non linear behaviour The book suggests new non linear models for the PLL components and applies the averaging method to analyse PLL The book presents the physical interpretation of the PLL operation locates the difficulties presented by its operation and suggests solutions to overcome these problems Finally it provides closed form expressions for all the important measures of the PLL and proposes new design criteria

Discrete-time Sliding Mode Control B. Bandyopadhyay, S. Janardhanan, 2005-10-17 Sliding mode control is a simple and yet robust control technique where the system states are made to confine to a selected subset With the increasing use of computers and discrete time samplers in controller implementation in the recent past discrete time systems and computer based control have become important topics This monograph presents an output feedback sliding mode control philosophy which can be applied to almost all controllable and observable systems while at the same time being simple enough as not to tax the computer too much It is shown that the solution can be found in the synergy of the multirate output sampling concept

and the concept of discrete time sliding mode control

PID Trajectory Tracking Control for Mechanical Systems

Youngjin Choi, Wan Kyun Chung, 2004-01-23 Though PID control has a long history as much as its life force since Ziegler and Nichols published the empirical tuning rules in 1942 surprisingly it has never been changed in the structure itself The strength of PID control lies in the simplicity lucid meaning and clear effect Though it must be a widely accepted controller for mechanical control systems it is still short of theoretical bases e.g optimality performance tuning rules automatic performance tuning method and output feedback PID control have not been clearly presented for mechanical control systems These subjects will be thoroughly discussed in this book There are many books of PID controller for the purpose of process control but it is hard to find a book on the characteristics of PID control for mechanical systems In the first place when nonlinear optimal control theory is applied to mechanical systems a class of Hamilton Jacobi HJ equations is derived as a result of optimization There are two methods to solve a class of HJ equations a direct method using an approximation and inverse method finding the performance index from a class of HJ equations Also there are two control methods according to the objective the set point regulation control and trajectory tracking control The trajectory tracking control is basically different from set point regulation one in that the desired configuration velocity and acceleration profiles according to time progress are added to the motion of mechanical system This book is focusing on an inverse optimization method and the trajectory tracking control system

Realization Theory of Discrete-Time Dynamical Systems

Tsuyoshi Matsuo, Yasumichi Hasegawa, 2003-10-08 This monograph extends Realization Theory to the discrete time domain It includes new results and constructs a new and very wide inclusion relation for various nonlinear dynamical systems After establishing some features of discrete time dynamical systems it presents results concerning systems which are proposed by the authors for the first time They introduce General Dynamical Systems Linear Representation Systems Affine Dynamical Systems Pseudo Linear Systems Almost Linear Systems and So called Linear Systems for discrete time and demonstrate the relationship between them and the other dynamical systems This book is intended for graduate students and researchers who study control theory

Advances in Communication Control Networks

Sophie Tarbouriech, Chaouki T. Abdallah, John Chiasson, 2004-09-22 The area of communication and computer networks has become a very active field of research by the control systems community in the last years Tools from convex optimization and control theory are playing increasing roles in efficient network utilization fair resource allocation and communication delay accommodation and the field of Networked Control systems is fast becoming a mainstay of control systems research and applications This carefully edited book brings together solicited contributions from experts in the various areas of communication control networks referring to both networks under control control in networks as well as networked control systems control over networks The aim of this book is to reverse the trend of fragmentation and specialization in Communication Control Networks connecting various interdisciplinary research fields including control communication applied mathematics and computer science

Switched and Impulsive Systems

Zhengguo Li,Yengchai Soh,Changyun Wen,2005-02-16 In this volume the important concept of switched and impulsive control is discussed with a wide field of applications in the analysis and control of complex systems This monograph provides the reader with a comprehensive coverage of switched and impulsive systems including new original work with various applications such as switched server systems scalable video coding systems chaotic based secure communication or quality of service on the internet Switched and Impulsive Systems can be used as a reference or a text for a course at graduate level

Hybrid Estimation of Complex Systems Michael W. Hofbaur,2005-06-09 This monograph provides a tool set for hybrid estimation that can successfully monitor the behavior of complex artifacts with a large number of possible operational and failure modes such as production plants automotive or aeronautic systems and autonomous robots For this purpose ideas from the fields of System Theory and Artificial Intelligence are taken and hybrid estimation is reformulated as a search problem This allows to focus the estimation onto highly probably operational modes without missing symptoms that might be hidden among the noise in the system Additionally a novel approach to continue hybrid estimation in the presence of unknown behavioral modes and to automate system analysis and synthesis tasks for on line operation are presented This leads to a flexible model based hybrid estimation scheme for complex artifacts that robustly copes with unforeseen situations

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