

Controlling Rc Vehicles With Your Computer Using Labview

R Sandford

Controlling Rc Vehicles With Your Computer Using Labview:

Soft Computing Applications Valentina Emilia Balas, Lakhmi C. Jain, Branko Kovačević, 2015-11-02 These volumes constitute the Proceedings of the 6th International Workshop on Soft Computing Applications or SOFA 2014 held on 24 26 July 2014 in Timisoara Romania This edition was organized by the University of Belgrade Serbia in conjunction with Romanian Society of Control Engineering and Technical Informatics SRAIT Arad Section The General Association of Engineers in Romania Arad Section Institute of Computer Science Iasi Branch of the Romanian Academy and IEEE Romanian Section The Soft Computing concept was introduced by Lotfi Zadeh in 1991 and serves to highlight the emergence of computing methodologies in which the accent is on exploiting the tolerance for imprecision and uncertainty to achieve tractability robustness and low solution cost Soft computing facilitates the use of fuzzy logic neurocomputing evolutionary computing and probabilistic computing in combination leading to the concept of hybrid intelligent systems The combination of such intelligent systems tools and a large number of applications introduce a need for a synergy of scientific and technological disciplines in order to show the great potential of Soft Computing in all domains The conference papers included in these proceedings published post conference were grouped into the following area of research Image Text and Signal Processing li Intelligent Transportation Modeling and Applications Biomedical Applications Neural Network and Applications Knowledge Based Technologies for Web Applications Cloud Computing Security Algorithms and Computer Networks Knowledge Based Technologies Soft Computing Techniques for Time Series Analysis Soft Computing and Fuzzy Logic in Biometrics Fuzzy Applications Theory and Fuzzy Control Bussiness Process Management Methods and Applications in Electrical Engineering The volumes provide useful information to professors researchers and graduated students in area of soft computing techniques and applications as they report new research work on challenging issues **Development of a** system for selective pasture care by an autonomous mobile machine Benjamin Seiferth, 2020-06-01 This book examines the possibility of automating pasture care by fusing conventional technologies with modern sensor technologies including the accompanying electrification It subsequently explores the feasibility and benefits of such a system on the basis of a prototype The overall challenge in fodder production and in milk and meat production is to shift the focus away from the economic aspects and toward achieving a better balance with ecological and societal aspects In the future pastureland will become an increasingly valuable resource Good pasture turf is the basis of high grazing performance and an efficient grazing farm reduced quantity and quality of pasture forage are chiefly due to insufficient pasture care The prototype developed and discussed here based on a commercially available remote controlled mulcher performs the selective pasture maintenance needed for precision farming The vehicle has been upgraded with a GPS system for automatic guidance while a 2D laser scanner is used to localise relevant spots in real time. The pasture maintenance operations include mulching of un grazed spots and reseeding of damage done by footsteps The book presents the results of field tests on effective spot detection and

Aschemann,2008-05-01 The book New Approaches in Automation and Robotics Harald Aschemann,2008-05-01 The book New Approaches in Automation and Robotics offers in 22 chapters a collection of recent developments in automation robotics as well as control theory It is dedicated to researchers in science and industry students and practicing engineers who wish to update and enhance their knowledge on modern methods and innovative applications. The authors and editor of this book wish to motivate people especially under graduate students to get involved with the interesting field of robotics and mechatronics. We hope that the ideas and concepts presented in this book are useful for your own work and could contribute to problem solving in similar applications as well It is clear however that the wide area of automation and robotics can only be highlighted at several spots but not completely covered by a single book

Automation and Control Trends Pedro Ponce, Arturo Molina, Luis Ibarra, 2016-10-12 This book is an overview of the different paths automation and control engineering have taken lately from a modern point of view Built up with example chapters this book provides some insight into the use of artificial intelligence and control theory on manufacturing comfort analysis reliability of modern digital systems and the use of unusual reference and feedback signals as those coming from the brain Nonetheless some chapters are also devoted to a more traditional point of view of control theory addressing complex problems where human intervention must be limited Overall this book is an effort to show that modern automation and control engineering are comprised by many diverse areas which should interact in order to provide a complete result In this way as the systems become more complex and the control objectives more subjective both formal analytic and intelligent approaches should be seen as complementary tools not unrelated competitors. This books aim is precisely that of showing how broad and diverse the control objectives have become and how the abilities of the control engineer should be extended

Cooperative Robots and Sensor Networks 2014 Anis Koubaa, Abdelmajid Khelil, 2014-05-21 This book is the second volume on Cooperative Robots and Sensor Networks The primary objective of this book is to provide an up to date reference for cutting edge studies and research trends related to mobile robots and wireless sensor networks and in particular for the coupling between them Indeed mobile robots and wireless sensor networks have enabled great potentials and a large space for ubiquitous and pervasive applications Robotics and wireless sensor networks have mostly been considered as separate research fields and little work has investigated the marriage between these two technologies However these two technologies share several features enable common cyber physical applications and provide complementary support to each other The book consists of ten chapters organized into four parts The first part of the book presents three chapters related to localization of mobile robots using wireless sensor networks Two chapters presented new solutions based Extended Kalman Filter and Particle Filter for localizing the robots using range measurements with the sensor network The third chapter presents a survey on mobility assisted localization techniques in wireless sensor networks The second part of the book deals with cooperative robots and sensor networks applications. One chapter presents a comprehensive overview of major

applications coupling between robots and sensor networks and provides real world examples of their cooperation Two other chapters present applications for underwater robots and sensor networks Unmanned Aerial Vehicles and Multidisciplinary Applications Using AI Techniques Thusnavis, Bella Mary I., Sagayam, K. Martin, Elngar, Ahmed A., 2022-05-27 Unmanned aerial vehicles UAVs and artificial intelligence AI are gaining the attention of academic and industrial researchers due to the freedoms that UAVs afford when operating and monitoring activities remotely Applying machine learning and deep learning techniques can result in fast and reliable outputs and have helped in real time monitoring data collection and processing and prediction UAVs utilizing these techniques can become instrumental tools for computer wireless networks smart cities military applications agricultural sectors and mining Unmanned Aerial Vehicles and Multidisciplinary Applications Using AI Techniques is an essential reference source that covers pattern recognition machine and deep learning based methods and other AI techniques and the impact they have when applied to different real time applications of UAVs It synthesizes the scope and importance of machine learning and deep learning models in enhancing UAV capabilities solutions to problems and numerous application areas Covering topics such as vehicular surveillance systems yield prediction and human activity recognition this premier reference source is a comprehensive resource for computer scientists AI engineers data scientists agriculturalists government officials military leaders business managers and leaders students and faculty of higher education academic libraries academicians and researchers in computer science computer vision pattern recognition imaging and engineering **Technological Developments in Education and Automation** Magued Iskander, Vikram Kapila, Mohammad A. Karim, 2010-01-30 Technological Developments in Education and Automation includes set of rigorously reviewed world class manuscripts dealing with the increasing role of technology in daily lives including education and industrial automation Technological Developments in Education and Automation contains papers presented at the International Conference on Industrial Electronics Technology Automation and the International Conference on Engineering Education Instructional Technology Assessment and E learning which were part of the International Joint Conferences on Computer Information and Systems Sciences and Engineering **Smart Industry &** Smart Education Michael E. Auer, Reinhard Langmann, 2018-07-24 The REV conference aims to discuss the fundamentals applications and experiences in remote engineering virtual instrumentation and related new technologies as well as new concepts for education on these topics including emerging technologies in learning MOOCs MOOLs Open Resources and STEM pre university education In the last 10 years remote solutions based on Internet technology have been increasingly deployed in numerous areas of research science industry medicine and education With the new focus on cyber physical systems Industry 4 0 Internet of Things and the digital transformation in industry economy and education the core topics of the REV conference have become indispensable elements of a future digitized society REV 2018 which was held at the University of Applied Sciences in Duesseldorf from 21 23 March 2018 addressed these topics as well as state of the art and

<u>Learning with LabVIEW 8</u> Robert H. Bishop, 2007 The defacto industry standard for test measurement and automation software solutions LabVIEW 8 delivers the graphical programming capabilities that allow users to design programmable software solutions to problems and lab experiments This version includes new chapter covering LabVIEW MathScript and an upgrade to Chapter 11 Analysis to reflect 150 new and enhanced analysis VIs A new Appendix has been added to include exciting innovative developments with Sound Card API LabVIEW Project and Shared Variables For electrical engineers and those involved in measurement and instrumentation **Innovation, Communication and Engineering** Teen-Hang Meen, Stephen Prior, Artde Lam, 2013-10-08 This volume represents the proceedings of the 2013 International Conference on Innovation Communication and Engineering ICICE 2013 This conference was organized by the China University of Petroleum Huadong East China and the Taiwanese Institute of Knowledge Innovation and was held in Qingdao Shandong P R China Introduction to Engineering Lina Karam, Naji Mounsef, 2008-09-08 This lecture provides a October 26 November 1 20 hands on glimpse of the field of electrical and computer engineering The broad range of hands on applications utilize LabVIEW and the NI SPEEDY 33 hardware to explore concepts such as basic computer input and output basic robotic principals and introductory signal processing and communication concepts such as signal generation modulation music speech and audio and image video processing These principals and technologies are introduced in a very practical way and are fundamental to many of the electronic and computerized devices we use today Some examples include audio level meter and audio effects music synthesizer real time autonomous robot image and video analysis and DTMF modulation found in touch tone telephone systems Table of Contents Getting Familiar with LabVIEW and SPEEDY 33 Applications using LEDs and Switches using the SPEEDY 33 Noise Removal Music Equalizer Telephone Digital Audio Effects Echo and Reverb Music Composer Introduction to Robotics AM Radio Modem Digital Image Processing Fundamentals Applications using USB

Camera Appendix VIs at a Glance Technological Innovation for Value Creation Luis M. Camarinha-Matos, Ehsan Shahamatnia, Gonçalo Nunes, 2012-02-23 This book constitutes the refereed proceedings of the Third IFIP WG 5.5 SOCOLNET Doctoral Conference on Computing Electrical and Industrial Systems DoCEIS 2012 held in Costa de Caparica Portugal in February 2012 The 65 revised full papers were carefully reviewed and selected from numerous submissions They cover a wide spectrum of topics ranging from collaborative enterprise networks to microelectronics. The papers are organized in topical sections on collaborative systems service orientation knowledge and content management human interaction Petri nets smart systems robotic systems perceptional systems signal processing energy renewable energy energy smart grid power electronics electronics optimization in electronics telecommunications and electronics and electronic materials The book also includes papers from the Workshop on Data Anaylsis and Modeling Retina in Health and Disease Over-height Collision Protection System of Sandwich Polymer Composites Integrated with Remote Monitoring for Concrete Bridge Girders, 2008 One of the common damages in existing highway bridges is the damage at the bottom corners or edges of the reinforced concrete beams or box girders induced by an impact of trucks exceeding the allowable height clearance of the bridges In this study a collision protection and scarifying system is developed and it utilizes advanced materials structures to protect highway bridge girders The proposed collision protection and scarifying system is in a new I Lam Impact Laminate configuration and bolted and or bonded to the bottom portions or edges of concrete girders The I Lam panels are made of a composite sandwich construction with multi layer aluminum honeycomb core and top and bottom thin face sheets and they are developed designed specifically for impact damage protection of bridge girders e g concrete girders Design criteria and guideline for I Lam are developed and the analysis optimal design and guality control tests of the collision protection system are conducted Smart piezoelectric sensors are integrated with the I Lam panels for monitoring the performance of the collision protection system The collision protection system is implemented in an identified bridge The developed smart bilayer honeycomb I Lam sandwich is capable of reducing the transferred contact force dramatically absorbing mitigating impact energy protecting the underneath concrete structures by system scarifying and core crushing and monitoring the impact incident with smart piezoelectric sensors and it is applicable to protecting other structures e.g. steel girders columns from accidental vehicle impact in the highways Proceedings of the 11th National Technical Seminar on Unmanned System Technology 2019 Zainah Md Zain, Hamzah Ahmad, Dwi Pebrianti, Mahfuzah Mustafa, Nor Rul Hasma Abdullah, Rosdiyana Samad, Maziyah Mat Noh, 2020-07-07 This book includes research papers from the 11th National Technical Symposium on Unmanned System Technology Covering a number of topics including intelligent robotics novel sensor technology control algorithms acoustics signal processing imaging techniques biomimetic robots green energy sources and underwater communication backbones and protocols it will appeal to researchers developing marine technology solutions and policy makers interested in technologies to facilitate the exploration of coastal and oceanic regions

Proceedings of First International Conference on Smart System, Innovations and Computing Arun K.

Somani, Sumit Srivastava, Ankit Mundra, Sanyog Rawat, 2018-01-08 The edited volume contains original papers contributed to 1st International Conference on Smart System Innovations and Computing SSIC 2017 by researchers from different countries The contributions focuses on two main areas i e Smart Systems Innovations which includes applications for smart cities smart grid social computing and privacy challenges with their theory specification design performance and system building And second Computing of Complex Solutions which includes algorithms security solutions communication and networking approaches The volume provides a snapshot of current progress in related areas and a glimpse of future possibilities This volume is useful for researchers Ph D students and professionals working in the core areas of smart systems innovations and computing NASA Tech Briefs ,2006 Eureka ,2002 Control Solutions ,2002

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