(b) We can solve the differential equation analytically. We separate variables and integrate. We get

$$\int (y-2)(y+1) dy = \int dt$$

$$\frac{y^3}{3} - \frac{y^2}{2} - 2y = t + c.$$

where c is a constant. Using y(0) = 1/2, we get c = 13/12. Therefore the solution to the initial-value problem is the unique solution y(r) that satisfies the equation

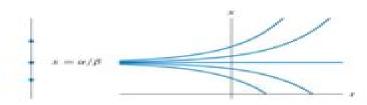
$$4y^3 - 6y^2 - 24y - 24t + 13 = 0$$

with -1 < y(t) < 2. It is not easy to solve this equation explicitly. However, in order to obtain the domain of this solution, we substitute y = -1 and y = 2 into the equation, and we get t = -9/8 and t = 9/8 respectively.

45. One assumption of the model is that, if no people are present, then the time between trains decreases at a constant rate. Hence the term -α represents this assumption. The parameter α should be positive, so that -α makes a negative contribution to dx/dt.

The term βx represents the effect of the passengers. The parameter β should be positive so that βx contributes positively to dx/dt.

- (a) Solving βx α = 0, we see that the equilibrium point is x = α/β.
 - (b) Since f(x) = βx − ω is positive for x > ω/β and negative for x < ω/β, the equilibrium point is a source.</p>
 - Gelt med GdD



(e) We separate the variables and integrate to obtain

$$\int \frac{dx}{\beta x - \alpha} = \int dt$$

$$\frac{1}{\beta} \ln |\beta x - \alpha| = t + c,$$

which yields the general solution $x(t) = \alpha/\beta + ke^{\beta t}$, where k is any constant.

47. Note that the only equilibrium point is a source. If the initial gap between trains is too large, then x will increase without bound. If it is too small, x will decrease to zero. When x = 0, the two trains are next to each other, and they will stay together since x < 0 is not physically possible in this problem.</p>

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mathematician appearing in the list of references I have included also some results of my own that did not find their way into monographs in the past I have done research in this direction for more than 25 years and have given graduate courses about some of the topics covered for many years at the Budapest University of Technology and also at the Universidad Central de Venezuela in Caracas I hope that people interested in differential equations and applications may use this experience Some may say that periodic solutions of ODEs has been a closed chapter of mathematics for some time **Box Splines** Carl de Boor, Klaus Höllig, Sherman Riemenschneider, 2013-03-09 Compactly supported smooth piecewise polynomial functions provide an efficient tool for the approximation of curves and surfaces and other smooth functions of one and several arguments Since they are locally polynomial they are easy to evaluate Since they are smooth they can be used when smoothness is required as in the numerical solution of partial differential equations in the Finite Element method or the modeling of smooth sur faces in Computer Aided Geometric Design Since they are compactly supported their linear span has the needed flexibility to approximate at all and the systems to be solved in the construction of approximations are banded The construction of compactly supported smooth piecewise polynomials becomes ever more difficult as the dimension s of their domain G IRs i e the number of arguments increases In the univariate case there is only one kind of cell in any useful partition namely an interval and its boundary consists of two separated points across which polynomial pieces would have to be matched as one constructs a smooth piecewise polynomial function. This can be done easily with the only limitation that the num ber of smoothness conditions across such a breakpoint should not exceed the polynomial degree since that would force the two joining polynomial pieces to coincide In particular on any partition there are nontrivial compactly supported piecewise polynomials of degree k and in C k l of which the univariate B spline is the most useful example Theory of Incompressible Nonviscous Fluids Carlo Marchioro, Mario Pulvirenti, 2012-12-06 Fluid dynamics is an ancient science incredibly alive today Modern technol ogy and new needs require a deeper knowledge of the behavior of real fluids and new discoveries or steps forward pose quite often challenging and diffi cult new mathematical oblems In this framework a special role is played by incompressible nonviscous sometimes called perfect flows This is a mathematical model consisting essentially of an evolution equation the Euler equation for the velocity field of fluids Such an equation which is nothing other than the Newton laws plus some additional structural hypo theses was discovered by Euler in 1755 and although it is more than two centuries old many fundamental questions concerning its solutions are still open In particular it is not known whether the solutions for reasonably general initial conditions develop singularities in a finite time and very little is known about the long term behavior of smooth solutions These and other basic problems are still open and this is one of the reasons why the mathe matical theory of perfect flows is far from being completed Incompressible flows have been attached by many distinguished mathe maticians with a large variety of mathematical techniques so that today this field constitutes a very rich and stimulating part of applied mathematics **Nonlinear Problems of Elasticity** Stuart Antman, 2013-03-14 The

scientists of the seventeenth and eighteenth centuries led by Jas Bernoulli and Euler created a coherent theory of the mechanics of strings and rods undergoing planar deformations They introduced the basic con cepts of strain both extensional and flexural of contact force with its components of tension and shear force and of contact couple They extended Newton's Law of Motion for a mass point to a law valid for any deformable body Euler formulated its independent and much subtler complement the Angular Momentum Principle Euler also gave effective variational characterizations of the governing equations These scientists breathed life into the theory by proposing formulating and solving the problems of the suspension bridge the catenary the velaria the elastica and the small transverse vibrations of an elastic string The level of difficulty of some of these problems is such that even today their descriptions are sel dom vouchsafed to undergraduates The realization that such profound and beautiful results could be deduced by mathematical reasoning from fundamental physical principles furnished a significant contribution to the intellectual climate of the Age of Reason At first those who solved these problems did not distinguish between linear and nonlinear equations and so were not intimidated by the latter By the middle of the nineteenth century Cauchy had constructed the basic framework of three dimensional continuum mechanics on the founda tions built by his eighteenth century predecessors Global Bifurcation in Variational Inequalities Vy Khoi Le, Klaus Schmitt, 2013-12-01 Bifurcation Problems for Variational Inequalities presents an up to date and unified treatment of bifurcation theory for variational inequalities in reflexive spaces and the use of the theory in a variety of applications such as obstacle problems from elasticity theory unilateral problems torsion problems equations from fluid mechanics and quasilinear elliptic partial differential equations The tools employed are the tools of modern nonlinear analysis This book is accessible to graduate students and researchers who work in nonlinear analysis nonlinear partial differential equations and additional research disciplines that use nonlinear mathematics

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