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Initial Max. deformation

The maximum force $F = kx$ occurs when x is a maximum with $\dot{x} = 0$.

$$U_1 + \Delta T = mgs - \frac{1}{2}kx^2 = 0, \quad x = \frac{2mg}{k}$$

$$\text{So } F = kx = 2mg$$

$$3/129 \quad T_A + V_{A-0} = T_C : 0 + 2mgR = \frac{1}{2}mv_C^2, \quad v_C^2 = 4gR$$

$$(a) \quad \Sigma F_n = ma_n : N_B = m \frac{4gR}{R} = 4mg$$

$$(b) \quad T_A + V_{A-C} = T_C : 0 + 3mgR = \frac{1}{2}mv_C^2, \quad v_C^2 = 6gR$$

$$\Sigma F_n = ma_n : N_C - mg = m \frac{6gR}{R}$$

$$N_C = 7mg$$

(c) Coll. stopping point E:

$$T_A + V_{A-E} = T_E$$

$$0 + 2mgR - mg\left(\frac{1}{2}\right) - \mu_k \frac{15}{2}mg = 0$$

$$s = \frac{4R}{1 + \mu_k 15}$$

(Note: Normal force on incline is)

$$N = mg \cos 30^\circ = \frac{\sqrt{3}}{2}mg$$

3/130 Let s = distance down incline before reversal of direction.

$$U_1 + \Delta T = 100(2)(10 + s - s) - 200(10 + s - s)\frac{5}{13} = 1046 \text{ ft}\cdot\text{lb}$$

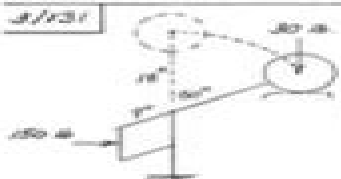
$$\Delta T = \frac{1}{2} \frac{350}{32.2} [v^2 - (17)^2] = 4.66v^2 - 377 \text{ ft}\cdot\text{lb}$$

$$U_1 + \Delta T : 1046 = 4.66v^2 - 377$$

$$v = 17.45 \text{ ft/sec}$$

The initial kinetic energy is positive regardless of the velocity direction.

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$$U_1 + \Delta T$$

$$150\left(\frac{1}{2}g \sin 60^\circ\right) - 30\frac{1}{2}g \sin 60^\circ$$

$$= \frac{1}{2} \frac{150}{32.2} (v^2 - 0)$$

$$v^2 = 160.8, \quad v = 12.68 \text{ m/sec}$$

$$3/132 \quad U_1 + \Delta T : mg(0.8 - 1.8 \cos 60^\circ)$$

$$= \frac{1}{2}m(12^2 - 9^2)$$

$$R(1)(0.20) = \frac{1}{2}(12^2 - 9^2), \quad 12^2 = 12.92, \quad 12 = 3.59 \text{ m/s}$$

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$$+\uparrow \Sigma F = 0 : 9810 - 4T = 0, \quad T = 2450 \text{ N}$$

Length of cable $L = 4s_0 + \text{constants}$

$$L = 4v_0 = 4(3) = 12 \text{ m/s}$$

$$P_{\text{out}} = -T\dot{L} = -2450(12) = 29400 \text{ watts}$$

$$\text{or } P_{\text{out}} = 29.4 \text{ kW}$$

$$C = \frac{P_{\text{out}}}{P_{\text{in}}}, \quad P_{\text{in}} = \frac{P_{\text{out}}}{C} = \frac{29.4}{0.8}$$

$$P_{\text{in}} = 36.8 \text{ kW}$$

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$$U_1 + \Delta T (\text{system})$$

$$\text{First interval: } 30(9.81)(1.2) - [30(9.81)(0.5 + 1.224)] \frac{1}{2} = \frac{1}{2} 30 v^2 + \frac{1}{2} 30 (10)^2$$

$$v^2 = 6.076 \text{ m/s}^2, \quad v = 2.447 \text{ m/s}$$

$$\text{Second interval: } 15(9.81)(2) - [30(9.81)(0.5 + 1.224)] \frac{1}{2} = 0 - \frac{1}{2} 15 (2.447)^2$$

$$- \frac{1}{2} 30 \left(\frac{5.897}{2}\right)^2$$

$$s = 2.18 \text{ m}, \quad S = \frac{1}{2}(1.2 + 2.18) = 1.69 \text{ m}$$

$$3/135 \quad U_1 + \Delta T : -\int_0^0 (3x^2 + 60x) dx = \frac{1}{2} \frac{450}{32.2} (0 - v^2) 12$$

$$x^2 + 20x^2 \Big|_0^0 = \frac{555}{32.2} v^2, \quad v \text{ in ft/sec.}$$

$$v^2 = \frac{32.2}{555} (60 + 480) = 60.82 \text{ (ft/sec)}^2, \quad v = 7.80 \text{ ft/sec}$$

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$$\Theta = \tan^{-1} \frac{6}{100} = 3.43^\circ$$

$$U_1 + \Delta T : U_1 + mgh = \frac{1}{2} m (v_1^2 + v_2^2)$$

$$U_1 = -1400(9.81)(200 \sin 3.43^\circ)$$

$$+ \frac{1}{2} 1400 \left[\left(\frac{20}{5.28}\right)^2 + \left(\frac{100}{5.28}\right)^2 \right]$$

$$= -683,000 \text{ J} \quad \text{or} \quad -683 \text{ kJ}$$

$$\text{Energy lost } Q = 683 \text{ kJ}$$

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The power output of the drivetrain is

$$P_{\text{out}} = Fv = 540 \left(\frac{30}{3.6}\right) = 14,400 \text{ W}$$

The power input to the drivetrain:

$$P_{\text{in}} = \frac{P_{\text{out}}}{\epsilon} = \frac{14,400}{0.70} = 20,571 \text{ W}$$

$$\text{So the motor output } P = 20.6 \text{ kW}$$

Meriam And Kraige Dynamics 7th Edition Solution

James L. Meriam, L. G. Kraige



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Engineering Mechanics James L. Meriam, L. G. Kraige, 2012-03-19 The 7th edition continues to provide the same high quality material seen in previous editions. It provides extensively rewritten updated prose for content clarity, superb new problems in new application areas, outstanding instruction on drawing free body diagrams, and new electronic supplements to assist learning and instruction.

Wind Energy Explained James F. Manwell, Emmanuel Branlard, Jon G. McGowan, Bonnie Ram, 2024-06-10 Authoritative and bestselling textbook detailing the many aspects of using wind as an energy source. Wind Energy Explained provides complete and comprehensive coverage on the topic of wind energy, starting with general concepts like the history of and rationale for wind energy and continuing into specific technological components and applications along with the new recent developments in the field. Divided into 16 chapters, this edition includes up to date data, diagrams, and illustrations, boasting an impressive 35% new material, including new sections on metocean design conditions, wind turbine design, wind power plants, and the electrical system, fixed and floating offshore wind turbines, project development, permitting, and environmental risks, and benefits, turbine installation, operation, and maintenance, and high penetration wind energy systems and power to X. Wind Energy Explained also includes information on Modern wind turbines, covering the design and their many components, such as the rotor drive train and generator, Aerodynamics of wind energy, covering one dimensional momentum theory, the Betz limit, and ideal horizontal axis wind turbine with wake rotation, Environmental external design conditions, such as wind waves, currents, tides, salinity, floating ice, and many more. Commonly used materials and components, such as steel, composites, copper, and concrete, plus machinery elements, such as shafts, couplings, bearings, and gears. Modern design methods, including probabilistic design, Environmental effects and mitigation strategies for wind project siting, and the role of public engagement in the development process. This book offers a complete examination of one of the most promising sources of renewable energy and is a great introduction to this cross disciplinary field for practicing engineers. It may also be used as a textbook resource for university level courses in wind energy, both introductory and advanced.

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A Primer in Fluid Mechanics Dynamics of Flows in One Space Dimension Jr. Brower, 2024-11-01 This distinctive text presents the basic principles of fluid mechanics by means of one dimensional flow examples differing significantly in style and content from other books A Primer in Fluid Mechanics contains an overview of fluid properties and the kinetic theory of gases information on the fundamental equations of fluid mechanics including historical references and background information introductory discussions on fluid properties and fluid statics a comprehensive chapter on compressible flow a variety of applications on non steady flow including non steady gas dynamics a brief introduction to acoustics Novel provisos in the text include an analysis of the static stability of a floating two dimensional parabolic section viscous flow through an elastic duct several geometries in non steady tank draining including a singular perturbation problem Chapters also discuss physical properties atmospheric stability thermodynamics energy and momentum equations dimensional analysis and historical perspectives of flows in pipes and conduits A Primer in Fluid Mechanics offers a rigorous text for the curious student and for the research engineer seeking a readily available guide to the more refined treatments in the literature supporting classical and current discussions as well as theoretical and practical concepts

Books in Print Supplement, 1994

Essentials of Strength Training and Conditioning Thomas R. Baechle, Roger W. Earle, National Strength & Conditioning Association (U.S.), 2008 Now in its third edition Essentials of Strength Training and Conditioning is the most comprehensive reference available for strength and conditioning professionals In this text 30 expert contributors explore the scientific principles concepts and theories of strength training and conditioning as well as their applications to athletic performance Essentials of Strength Training and Conditioning is the most preferred preparation text for the Certified Strength and Conditioning Specialist CSCS exam The research based approach extensive exercise technique section and unbeatable accuracy of Essentials of Strength Training and Conditioning make it the text readers have come to rely on for CSCS exam preparation The third edition presents the most current strength training and conditioning research and applications in a logical format designed for increased retention of key concepts The text is organized into five sections The first three sections provide a theoretical framework for application in section 4 the program design portion of the book The final section offers practical strategies for administration and management of strength and conditioning facilities Section 1 chapters 1 through 10 presents key topics and current research in exercise physiology biochemistry anatomy biomechanics endocrinology sport nutrition and sport psychology and discusses applications for the design of safe and effective strength and conditioning programs Section 2 chapters 11 and 12 discusses testing and evaluation including the principles of test selection and administration as well as the scoring and interpretation of results Section 3 chapters 13 and 14 provides techniques for warm up stretching and resistance training exercises For each exercise accompanying photos and instructions

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The British National Bibliography Arthur James Wells, 1998

Climbing and Walking Robots Manuel Armada, Pablo González de Santos, 2006-01-16 Interest in climbing and walking robots CLAWAR has increased remarkably over recent years Novel solutions for complex and very diverse application fields exploration intervention in severe environments personal services emergency rescue operations

transportation entertainment medical etc have been anticipated by great progress in this area of robotics This book contains the proceedings of the 7th Climbing and Walking Robots 2004 CLAWAR 2004 Conference offering the international scientific community one of the most excellent forums for academics researchers and industrialists interested in this motivating area of climbing and walking robots It provides a wide forum of original state of the art contributions from various industrial and new emerging research fields presenting a full picture of climbing and walking robots The conference held in Madrid Spain September 22-24 2004 was organized by the Thematic Network CLAWAR 2 and funded by the European Commission under the GROWTH Program

XVIII International Coal Preparation Congress Vladimir Litvinenko, 2016-10-21 This book gathers technical and scientific articles by leading experts from 15 countries and originally presented at the world's most prestigious forum on coal preparation the XVIII International Coal Preparation Congress Topics addressed include the mineral resources basis of the coal industry problems and prospects of development in the coal industry crushing grinding screening and classification processes used at sorting plants coal processing and briquette factories review of plant designs and operations used around the world new developments in dense medium separators water based separation processes froth flotation and dewatering technologies and equipment for the dry separation of coal coal deep processing technologies and equipment energy generation as an area of coal deep processing and simulation and optimization software for separation processes In general the future of coal around the world is defined by its competitiveness As the cheapest form of fuel comparatively speaking coal undoubtedly continues to be in high demand around the world

32nd Aerospace Sciences Meeting & Exhibit: 94-0840 - 94-0872, 1994 *Online Solutions Manual for Engineering Mechanics* J. L. Meriam, 2003-03-27

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Solving Dynamics Problems in Maple by Brian Harper T/a Engineering Mechanics Dynamics 6th Edition by Meriam and Kraige Brian D. Harper,J. L. Meriam,L. G. Kraige,2006-12-15

Instructor's Solution Manual [for] Engineering Mechanics A. Bedford,Wallace L. Fowler,2005

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