



2/124 $v_{x=50'} = \sqrt{2g\left(\frac{50}{32.2}\right)^2} = \frac{5}{2}\sqrt{2g} \frac{\text{ft}}{\text{sec}}$
 $a_n = \frac{v^2}{r}$, where $r = \frac{[1 + (\frac{dy}{dx})^2]^{3/2}}{dy/dx} = \frac{[1 + (\frac{3}{200})^2]^{3/2}}{1/200}$
 $r_{x=50'} = 219 \text{ ft}$
 $a_n = \frac{25}{2} \cdot 2(32.2)/219 = 1.838 \text{ ft/sec}^2$

2/125 $a_n = v^2/r = 4^2/0.120 = 133.3 \text{ m/s}^2$
 $a_t = a_n \sin 4^\circ = 133.3 \sin 4^\circ = 9.307 \text{ m/s}^2$
 with a_t const., $v^2 = v_i^2 + a_t t$, $0 = 4^2 - 9.307 t$
 $t = \frac{4^2}{9.307} = 2.10(10^{-3}) \text{ s}$

2/126 $v_0 = 100 \text{ ft/sec}$

 (a) $a_n = g \cos 30^\circ = \frac{v^2}{r}$
 $r = \frac{100^2}{g \cos 30^\circ} = 359 \text{ ft}$
 $\dot{v} = -g \sin 30^\circ = -16.1 \text{ ft/sec}^2$
 (b) $a_n = g = \frac{v^2}{r}$
 $r = \frac{(100 \cos 30^\circ)^2}{32.2} = 233 \text{ ft}$
 $\dot{v} = 0$

2/127 The time t_{ap} to apex is found from
 $v_y = v_{y0} - gt$; $0 = 100 \sin 30^\circ - 32.2 t_{ap}$, $t_{ap} = 1.553 \text{ s}$
 So, $t = 1 \text{ sec}$ is before apex and $t = 2.5 \text{ sec}$ is after.
 (a) $t = 1 \text{ sec}$
 $x = v_x = 100 \cos 30^\circ = 86.6 \text{ ft/sec}$
 $v_y = 100 \sin 30^\circ - 32.2(1) = 17.8 \text{ ft/sec}$
 $v = \sqrt{v_x^2 + v_y^2} = 88.4 \text{ ft/sec}$
 $\theta = \tan^{-1} \frac{v_y}{v_x} = 11.41^\circ$
 $a_n = g \cos \theta = 32.2 \cos 11.41^\circ = 31.5 \text{ ft/sec}^2$
 $r = \frac{v^2}{a_n} = \frac{88.4^2}{31.5} = 248 \text{ ft}$
 $a_t = -g \sin \theta = -32.2 \sin 11.41^\circ = -6.48 \text{ ft/sec}^2$
 (b) $t = 2.5 \text{ sec}$
 $v_x = 86.6 \text{ ft/sec}$
 $v_y = 100 \sin 30^\circ - 32.2(2.5) = -39.5 \text{ ft/sec}$
 $v = \sqrt{v_x^2 + v_y^2} = 91.8 \text{ ft/sec}$
 $\theta = \tan^{-1} \frac{|v_y|}{v_x} = 17.40^\circ$
 $a_n = g \cos \theta = 32.2 \cos 17.40^\circ = 30.4 \text{ ft/sec}^2$
 $r = \frac{v^2}{a_n} = \frac{91.8^2}{30.4} = 278 \text{ ft}$
 $a_t = +g \sin \theta = +32.2 \sin 17.40^\circ = 10.70 \text{ ft/sec}^2$

2/128 
 $\dot{v} = a_t = 9.44 \sin 1.50^\circ - 12.90 = -12.65 \text{ m/s}^2$
 $a_n = g \cos \theta = 9.44 \cos 1.5^\circ = 9.457 \text{ m/s}^2$
 $a_n = \frac{v^2}{r} \Rightarrow r = \frac{v^2}{a_n} = \frac{(15.450/3.6)^2}{9.457}$
 $r = 1907 \text{ km}$

2/129 $a_n = 0.8g = \frac{v^2}{r} \Rightarrow v = \sqrt{0.8gr}$
 Car A: $v_A = \sqrt{0.8(9.8)(88)} = 26.3 \text{ m/s}$
 Car B: $v_B = \sqrt{0.8(9.8)(72)} = 23.8 \text{ m/s}$
 $t_A = \frac{s_A}{v_A} = \frac{\pi(88)}{26.3} = 10.52 \text{ s}$
 $t_B = \frac{s_B}{v_B} = \frac{\pi(72) + 2(4)}{23.8} = 10.86 \text{ s}$
 Car A will win the race!

2/130 Evaluate $y = y_0 + v_{y0}t - \frac{1}{2}gt^2$ at C:
 $0 = 150 + 0 - \frac{1}{2}(9.8)t^2$, $t = 3.05 \text{ sec}$
 Evaluate $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$ at C:
 $120 = 0 + 50(3.05) + \frac{1}{2}a_x(3.05)^2$, $a_x = -7.00 \text{ ft/sec}^2$
 At B: $\begin{cases} v_x = v_{x0} + a_x t: v_x = 50 - 7.00t \\ v_y = v_{y0} - gt: |v_y| = 32.2 \end{cases}$
 Set $v_x = |v_y|$ to obtain $t = 1.275 \text{ sec}$
 So at B: $v_x = |v_y| = 32.2(1.275) = 41.1 \text{ ft/sec}$
 The speed at B is $v = 41.1\sqrt{2} = 58.1 \text{ ft/sec}$
 $a_n = 32.2 \cos 45^\circ + 7.00 \cos 45^\circ = 27.7 \text{ ft/sec}^2$
 From $a_n = \frac{v^2}{r}$
 $r = \frac{v^2}{a_n} = \frac{(58.1)^2}{27.7} = 121.7 \text{ ft}$

2/131 For a_t const., $v_f^2 = v_i^2 + 2a_t s_{AB}$
 $v_f^2 = \frac{250^2}{3.6^2} + 2 \cdot \frac{250}{3.6} \cdot \frac{1500}{3.6} = 15625 + 19444.4 = 35069.4$
 $v_f = 187.3 \text{ m/s}$
 at B, $a_t = \frac{v_f^2}{r} = \frac{187.3^2}{1500} = 23.4 \text{ m/s}^2$
 $a = \sqrt{a_n^2 + a_t^2} = \sqrt{12.5^2 + 23.4^2} = 26.6 \text{ m/s}^2$

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Hamid D. Taghirad



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Engineering Applications of Dynamics Dean C. Karnopp, Donald L. Margolis, 2007-12-14 A GROUNDBREAKING TEXT THAT BRIDGES THE GAP BETWEEN THEORETICAL DYNAMICS AND INDUSTRY APPLICATIONS Designed to address the perceived failure of introductory dynamics courses to produce students capable of applying dynamic principles successfully both in subsequent courses and in practice Engineering Applications of Dynamics adopts a much needed practical approach designed to make the subject not only more relevant but more interesting as well Written by a highly respected team of authors the book is the first of its kind to tie dynamics theory directly to real world situations By touching on complex concepts only to the extent of illustrating their value in real world applications the authors provide students with a deeper understanding of dynamics in the engineering of mechanical systems Topics of interest include The formulation of equations in forms suitable for computer simulation Simulation examples of real engineering systems Applications to vehicle dynamics Lagrange's equations as an alternative formulation procedure Vibrations of lumped and distributed systems Three dimensional motion of rigid bodies with emphasis on gyroscopic effects Transfer functions for linearized dynamic systems Active control of dynamic systems A Solutions Manual with detailed solutions for all problems in this book is available at the Web site www.wiley.com/college/karnopp

Essentials of Dynamics and Vibrations John Billingsley, 2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler's equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects

Statics Meriam, J.L. (James L.), L. Glenn Kraige, 2008 Over the past 50 years Meriam Kraige's Engineering Mechanics Statics has established a highly respected tradition of excellence a tradition that emphasizes accuracy rigor clarity and applications Now in a Sixth Edition this classic text builds on these strengths adding a comprehensive course management system Wiley Plus to the text including an e text homework management animations of concepts and additional teaching and learning resources New sample problems new homework problems and updates to content make the book more accessible The Sixth Edition continues to provide a wide variety of high quality problems that are known for their accuracy realism applications and variety motivating students to learn and develop their problem solving skills To build necessary visualization and problem solving skills the Sixth Edition continues to offer comprehensive coverage of drawing free body diagrams the most important

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Principles of Engineering Mechanics Millard F. Beatty, 2005-11-30 Separation of the elements of classical mechanics into kinematics and dynamics is an uncommon tutorial approach but the author uses it to advantage in this two volume set. Students gain a mastery of kinematics first a solid foundation for the later study of the free body formulation of the dynamics problem. A key objective of these volumes which present a vector treatment of the principles of mechanics is to help the student gain confidence in transforming problems into appropriate mathematical language that may be manipulated to give useful physical conclusions or specific numerical results. In the first volume the elements of vector calculus and the matrix algebra are reviewed in appendices. Unusual mathematical topics such as singularity functions and some elements of tensor analysis are introduced within the text. A logical and systematic building of well known kinematic concepts, theorems and formulas illustrated by examples and problems is presented offering insights into both fundamentals and applications. Problems amplify the material and pave the way for advanced study of topics in mechanical design, analysis, advanced kinematics of mechanisms and analytical dynamics, mechanical vibrations and controls and continuum mechanics of solids and fluids. Volume I of Principles of Engineering Mechanics provides the basis for a stimulating and rewarding one term course for advanced undergraduate and first year graduate students specializing in mechanics, engineering science, engineering physics, applied mathematics, materials science and mechanical, aerospace and civil engineering. Professionals working in related fields of applied mathematics will find it a practical review and a quick reference for questions involving basic kinematics.

Stress, Strain, and Structural Dynamics Bingen Yang, 2005-02-25 CD ROM contains hundreds of MATLAB functions, computer programs for numerical and analytical solutions.

Principles of Vibration Analysis with Applications in Automotive Engineering Ronald L. Huston, C. Q. Liu, 2011-01-10 This book, written for practicing engineers, designers, researchers and students, summarizes basic vibration theory and established methods for analyzing vibrations. Principles of Vibration Analysis goes beyond most other texts on this subject as it integrates the advances of modern modal analysis, experimental testing and numerical analysis with fundamental theory. No other book brings all of these topics together under one cover. The authors have compiled these topics, compared them and provided experience with practical application. This must have book is a comprehensive resource that the practitioner will reference time and again.

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Engineering Dynamics Oliver M. O'Reilly, 2010-05-25 This Primer is intended to provide the theoretical background for the standard undergraduate mechanical engineering course in dynamics The book contains several worked examples and summaries and exercises at the end of each chapter to aid readers in their understanding of the material Teachers who wish to have a source of more detailed theory for the course as well as graduate students who need a refresher course on undergraduate dynamics when preparing for certain first year graduate school examinations and students taking the course will find the work very helpful

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Parallel Robots Hamid D. Taghirad, 2025-09-05 In today's rapidly evolving industrial landscape robotics has become essential for meeting the demands of large scale production Parallel robots with their closed loop kinematic structures offer unmatched precision rigidity and load bearing capabilities making them indispensable for tasks requiring high accuracy and efficiency This book explores the unique advantages of parallel robots providing a comprehensive resource

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Bibliography Arthur James Wells,1998 **Vibrations and Waves in Continuous Mechanical Systems** Peter Hagedorn,Anirvan DasGupta,2007-10-22 The subject of vibrations is of fundamental importance in engineering and technology Discrete modelling is sufficient to understand the dynamics of many vibrating systems however a large number of vibration phenomena are far more easily understood when modelled as continuous systems The theory of vibrations in continuous systems is crucial to the understanding of engineering problems in areas as diverse as automotive brakes overhead transmission lines liquid filled tanks ultrasonic testing or room acoustics Starting from an elementary level *Vibrations and Waves in Continuous Mechanical Systems* helps develop a comprehensive understanding of the theory of these systems and the tools with which to analyse them before progressing to more advanced topics Presents dynamics and analysis techniques for a wide range of continuous systems including strings bars beams membranes plates fluids and elastic bodies in one two and three dimensions Covers special topics such as the interaction of discrete and continuous systems vibrations in translating media and sound emission from vibrating surfaces among others Develops the reader s understanding by progressing from very simple results to more complex analysis without skipping the key steps in the derivations Offers a number of new topics and exercises that form essential steppingstones to the present level of research in the field Includes exercises at the end of the chapters based on both the academic and practical experience of the authors *Vibrations and Waves in Continuous Mechanical Systems* provides a first course on the vibrations of continuous systems that will be suitable for students of continuous system dynamics at senior undergraduate and graduate levels in mechanical civil and aerospace engineering It will also appeal to researchers developing theory and analysis within the field XVIII

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