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Roland Toth



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Parameter-Varying Systems Roland Toth, 2010-07-11 Through the past 20 years the framework of Linear Parameter Varying LPV systems has become a promising system theoretical approach to handle the control of mildly nonlinear and especially position dependent systems which are common in mechatronic applications and in the process industry The birth of this system class was initiated by the need of engineers to achieve better performance for nonlinear and time varying dynamics common in many industrial applications than what the classical framework of Linear Time Invariant LTI control can provide However it was also a primary goal to preserve simplicity and re use the powerful LTI results by extending them to the LPV case The progress continued according to this philosophy and LPV control has become a well established field with many promising applications Unfortunately modeling of LPV systems especially based on measured data which is called system identification has seen a limited development since the birth of the framework Currently this bottleneck of the LPV framework is halting the transfer of the LPV theory into industrial use Without good models that fulfill the expectations of the users and without the understanding how these models correspond to the dynamics of the application it is difficult to design high performance LPV control solutions This book aims to bridge the gap between modeling and control by investigating the fundamental questions of LPV modeling and identification It explores the missing details of the LPV system theory that have hindered the formulation of a well established identification framework *Applied Mechanics Reviews*, 1974

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Biological and Mathematical Sciences The chapters correspond to selected papers on special research themes which have been presented at BIOMAT 2013 International Symposium on Mathematical and Computational Biology which was held in the Fields Institute for Research in Mathematical Sciences Toronto Ontario Canada on November 04-08 2013 The treatment is both pedagogical and advanced in order to motivate research students as well as to fulfill the requirements of professional practitioners There are comprehensive reviews written by prominent scientific leaders of famous research groups

Control of Cyber-Physical Systems Danielle C. Tarraf, 2013-06-30 Cyber physical systems CPS involve deeply integrated tightly coupled computational and physical components These systems spanning multiple scientific and technological domains are highly complex and pose several fundamental challenges They are also critically important to society's advancement and security The design and deployment of the adaptable reliable CPS of tomorrow requires the development of a basic science foundation synergistically drawing on various branches of engineering mathematics computer science and domain specific knowledge This book brings together 19 invited papers presented at the Workshop on Control of Cyber Physical Systems hosted by the Department of Electrical Computer Engineering at The Johns Hopkins University in March

2013 It highlights the central role of control theory and systems thinking in developing the theory of CPS in addressing the challenges of cyber trust and cyber security and in advancing emerging cyber physical applications ranging from smart grids to smart buildings cars and robotic systems **Uncertainty Management for Robust Industrial Design in Aeronautics**

Charles Hirsch,Dirk Wunsch,Jacek Szumbarski,Łukasz Łaniewski-WoŃk,Jordi Pons-Prats,2018-07-21 This book covers cutting edge findings related to uncertainty quantification and optimization under uncertainties i e robust and reliable optimization with a special emphasis on aeronautics and turbomachinery although not limited to these fields It describes new methods for uncertainty quantification such as non intrusive polynomial chaos collocation methods perturbation methods as well as adjoint based and multi level Monte Carlo methods It includes methods for characterization of most influential uncertainties as well as formulations for robust and reliable design optimization A distinctive element of the book is the unique collection of test cases with prescribed uncertainties which are representative of the current engineering practice of the industrial consortium partners involved in UMRIDA a level 1 collaborative project within the European Commission s Seventh Framework Programme FP7 All developed methods are benchmarked against these industrial challenges Moreover the book includes a section dedicated to Best Practice Guidelines for uncertainty quantification and robust design optimization summarizing the findings obtained by the consortium members within the UMRIDA project All in all the book offers a authoritative guide to cutting edge methodologies for uncertainty management in engineering design covers a wide range of applications and discusses new ideas for future research and interdisciplinary collaborations Popular Science ,1947-03 Popular Science gives our readers the information and tools to improve their technology and their world The core belief that Popular Science and our readers share The future is going to be better and science and technology are the driving forces that will help make it better **Popular Science** ,1947-11 Popular Science gives our readers the information and tools to improve their technology and their world The core belief that Popular Science and our readers share The future is going to be better and science and technology are the driving forces that will help make it better **Adaptive High-order Methods**

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be better and science and technology are the driving forces that will help make it better

Deterministic and Stochastic Modeling in Computational Electromagnetics Dragan Poljak, Anna Susnjara, 2023-12-07 Deterministic and Stochastic Modeling in Computational Electromagnetics Help protect your network with this important reference work on cyber security Deterministic computational models are those for which all inputs are precisely known whereas stochastic modeling reflects uncertainty or randomness in one or more of the data inputs Many problems in computational engineering therefore require both deterministic and stochastic modeling to be used in parallel allowing for different degrees of confidence and incorporating datasets of different kinds In particular non intrusive stochastic methods can be easily combined with widely used deterministic approaches enabling this more robust form of data analysis to be applied to a range of computational challenges Deterministic and Stochastic Modeling in Computational Electromagnetics provides a rare treatment of parallel deterministic stochastic computational modeling and its beneficial applications Unlike other works of its kind which generally treat deterministic and stochastic modeling in isolation from one another it aims to demonstrate the usefulness of a combined approach and present particular use cases in which such an approach is clearly required It offers a non intrusive stochastic approach which can be incorporated with minimal effort into virtually all existing computational models Readers will also find A range of specific examples demonstrating the efficiency of deterministic stochastic modeling Computational examples of successful applications including ground penetrating radars GPR radiation from 5G systems transcranial magnetic and electric stimulation TMS and TES and more Introduction to fundamental principles in field theory to ground the discussion of computational modeling Deterministic and Stochastic Modeling in Computational Electromagnetics is a valuable reference for researchers including graduate and undergraduate students in computational electromagnetics as well as to multidisciplinary researchers engineers physicists and mathematicians

Modellprädiktive Regelung nichtlinearer Systeme mit Unsicherheiten Andreas Völz, 2016-10-20 Andreas Völz untersucht eines der vielseitigsten Regelungsverfahren für technische Prozesse und zeigt den Umgang mit Messunsicherheiten unbekannten Umwelteinflüssen sowie Modellungenauigkeiten auf Basierend auf der sogenannten Unscented Transformation die bislang insbesondere im Zusammenhang mit der Kalman Filterung ein Begriff ist können Unsicherheiten mithilfe des Erwartungswertes und der Kovarianzmatrix der nichtlinearen Systemdynamik präzisiert und im Kostenfunktional gewichtet werden Der Autor stellt einen neuen Ansatz für die modellprädiktive Regelung nichtlinearer Systeme mit stochastischen Unsicherheiten vor und kann anhand mehrerer Beispielsysteme nachweisen dass Beschränkungen auch in Gegenwart von Unsicherheiten zuverlässig eingehalten werden können

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