


3/1  $v_2^2 - v_1^2 = 2a(x_2 - x_1)$   
 $0^2 - \left(\frac{100}{3.2}\right)^2 = 2a_x(50)$ ,  $a_x = -7.72 \text{ m/s}^2$   


$\Sigma F_x = ma_x$ :  $-4F = 1500(-7.72)$   
 $F = 2870 \text{ N}$

3/2  $50(9.81) \text{ N}$   $\Sigma F_y = 0$ :  $N - 50(9.81) \cos 15^\circ = 0$   
 $N = 474 \text{ N}$  Throughout

(a)  $P = 0$   
 Equilibrium check:  
 $\Sigma F_x = 0$ :  $F - 50(9.81) \sin 15^\circ = 0$   
 $F = 127.9 \text{ N}$

$F_{\max} = \mu_s N = 0.2(474) = 94.8 \text{ N} < F$ : motion  $\checkmark$   
 $\Sigma F_x = ma_x$ :  $0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$   
 $a_x = -1.118 \text{ m/s}^2$

(b)  $P = 150 \text{ N}$ ; Equilibrium check:  
 $\Sigma F_y = 0$ :  $150 + F - 50(9.81) \sin 15^\circ = 0$


$F = -23.9 \text{ N}$ ,  $|F| < F_{\max}$  so no motion:  $a = 0$

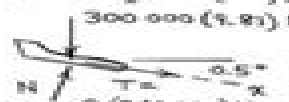
(c)  $P = 300 \text{ N}$ ; Equilibrium check yields  $F = -173.0 \text{ N}$   
 $|F| > F_{\max}$ , so motion  $\checkmark$ ,  $F = F_k \checkmark$ .  
 $\Sigma F_x = ma_x$ :  $300 - 0.15(474) - 50(9.81) \sin 15^\circ = 50a_x$   
 $a_x = 2.04 \text{ m/s}^2$

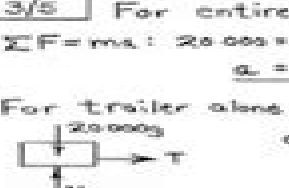
3/3  $80 \text{ lb}$   $\Sigma F_y = 0$ :  $N - 80 \cos 20^\circ = 0$   
 $N = 75.2 \text{ lb}$   
 $\Sigma F_x = ma_x$ :  
 $-0.25(75.2) - 80 \sin 20^\circ = \frac{80}{32.2} a$   
 $a = -18.58 \text{ ft/sec}^2$


$v = v_0 + at$ :  $0 = 30 - 18.58t$ ,  $t = 1.615 \text{ sec}$   
 $v^2 = v_0^2 + 2a(s - s_0)$ :  $0^2 = 30^2 + 2(-18.58)d$   
 $d = 24.2 \text{ ft}$

$v^2 = v_0^2 + 2a(s - s_0)$ :  $15^2 = 30^2 + 2(-18.58)d'$   
 $d' = 18.17 \text{ ft}$


3/4  $300,000(9.81) \text{ N}$   
  
 $\Sigma F_x = ma_x$ :  
 $3(240,000) - 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$   
 $a_x = 2.31 \text{ m/s}^2$

$v^2 = 2a_x s$ :  $\left(\frac{220}{3.6}\right)^2 = 2(2.31)s$ ,  $s_x = 807 \text{ m}$   
  
 $\Sigma F_x = ma_x$ :  
 $3(240,000) + 300,000(9.81) \sin \frac{1}{2}^\circ = 300,000 a_x$   
 $a_x = 2.49 \text{ m/s}^2$   
 $v^2 = 2a_x s$ :  $\left(\frac{220}{3.6}\right)^2 = 2(2.49)s$ ,  $s_x = 751 \text{ m}$

3/5 For entire unit:  $20,000 \text{ kg}$   $10,000 \text{ kg}$   
 $\Sigma F = ma$ :  $20,000 = 30,000a$   
 $a = 0.667 \text{ m/s}^2$   
  
 For trailer alone,  $T = 20,000(0.667) = 13,330 \text{ N}$   
 or  $T = 13.33 \text{ kN}$

3/6  $\Sigma F_x = ma_x$ :  $mg \sin 40^\circ - \mu_k mg \cos 40^\circ = ma$   
  
 $a = 9.81(\sin 40^\circ - \mu_k \cos 40^\circ)$   
 $= 6.31 - 7.51 \mu_k$

For constant accel.  $s = v_0 t + \frac{1}{2}at^2$ :  
 $20 = 0 + \frac{1}{2}(6.31 - 7.51 \mu_k)2.58^2$   
 $\mu_k = 0.0595$

3/7  $\Sigma F = ma$ :  $T - 100 = \frac{100}{32.2} a$   
 (a)  $T \uparrow$   $150 - T = \frac{100}{32.2} a$   
  
 $50 = \frac{200}{32.2} a$ ,  $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$

(b)  $150 - 100 = \frac{100}{32.2} a$ ,  $a = \frac{32.2}{2} = 16.10 \frac{\text{ft}}{\text{sec}^2}$   


# Meriam Dynamics Solutions Chapter 3

**James L. Meriam**



### **Meriam Dynamics Solutions Chapter 3:**

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**Dynamics - Formulas and Problems** Dietmar Gross, Wolfgang Ehlers, Peter Wriggers, Jörg Schröder, Ralf Müller, 2016-10-05 This book contains the most important formulas and more than 190 completely solved problems from Kinetics and Hydrodynamics It provides engineering students material to improve their skills and helps to gain experience in solving engineering problems Particular emphasis is placed on finding the solution path and formulating the basic equations Topics include Kinematics of a Point Kinetics of a Point Mass Dynamics of a System of Point Masses Kinematics of Rigid Bodies Kinetics of Rigid Bodies Impact Vibrations Non Inertial Reference Frames Hydrodynamics

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**Supplement to Accompany Engineering Mechanics: Dynamics, 5th Edition by Meriam & Kraige** Brian

Harper, 2001-11-26 If MathCad is the computer algebra system you need to use for your engineering calculations and graphical output Harper's Solving Dynamics Problems in MathCad is the reference that will be a valuable tutorial for your studies. Written as a guidebook for students taking the Engineering Mechanics course it will help you with your engineering assignments throughout the course. Over the past 50 years Meriam Kraige's Engineering Mechanics Dynamics has established a highly respected tradition of Excellence. A Tradition that emphasizes accuracy, rigor, clarity, and applications. Now completely revised, redesigned, and modernized, the new fifth edition of this classic text builds on these strengths, adding new problems and a more accessible student-friendly presentation. *Parallel Robots* Hamid D. Taghirad, 2025-09-05 In today's rapidly evolving industrial landscape, robotics has become essential for meeting the demands of large-scale production. Parallel robots, with their closed-loop kinematic structures, offer unmatched precision, rigidity, and load-bearing capabilities, making them indispensable for tasks requiring high accuracy and efficiency. This book explores the unique advantages of parallel robots, providing a comprehensive resource for engineers, researchers, and students interested in mastering their design, analysis, and control. Building on the success of its first edition, this second edition has been extensively restructured and updated to reflect over a decade of progress in robotics. It features expanded chapters on dynamics, new sections on simulation and calibration, and a detailed exploration of control techniques ranging from introductory linear methods to advanced force control. With nearly 45% updated references, the text ensures readers are equipped with cutting-edge knowledge. This book is both a comprehensive guide and a gateway to innovation, providing detailed insights into the design, simulation, calibration, and control of parallel robots. Whether you are a newcomer to robotics or an experienced professional, this text equips you with the knowledge to harness the full potential of parallel robots, helping you stay ahead in the dynamic field of industrial automation. **Engineering Education**, 1980 Applied Mechanics Reviews, 1972 **Statics and Dynamics** James L. Meriam, 1966 *Engineering Mechanics: Statics* James L. Meriam, 1997

*Sustainable and Resilient Communities* Stephen J. Coyle, 2011-05-12 Many of today's communities face an unprecedented struggle to adapt and maintain their environmental, economic, and social well-being in an era beleaguered by fiscal constraints, uncertainty about energy prices and supplies, rapid demographic shifts, and accelerated climate impacts. This step-by-step guidebook for urban planners and urban designers explains how to create and implement an actionable plan for making neighborhoods, communities, and regions more environmentally healthy, resource conserving, and economically resilient. *Sustainable and Resilient Communities* delineates measures for repairing, retrofitting, and transforming our built environments and supporting systems. *700 Solved Problems In Vector Mechanics for Engineers: Dynamics* Joseph F. Shelley, 1991-04 Suitable for 2nd-year college and university engineering students, this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course. It offers the comprehensive

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