

COMPUTATIONAL IMAGING AND VISION

# **Epipolar Geometry in Stereo, Motion and Object Recognition**

**A Unified Approach**

**Gang Xu and Zhengyou Zhang**

# Epipolar Geometry In Stereo Motion And Object Recognition A Unified Approach Computational Imaging And Vision

**Lei Shi**



## **Epipolar Geometry In Stereo Motion And Object Recognition A Unified Approach Computational Imaging And Vision:**

**Epipolar Geometry in Stereo, Motion and Object Recognition** Gang Xu,Zhengyou Zhang,1996-09-30 Appendix 164 3 A 3 A 1 Approximate Estimation of Fundamental Matrix from General Matrix 164 3 A 2 Estimation of Affine Transformation 165 4 RECOVERY OF EPIPOLAR GEOMETRY FROM LINE SEGMENTS OR LINES 167 Line Segments or Straight Lines 168 4 1 4 2 Solving Motion Using Line Segments Between Two Views 173 4 2 1 Overlap of Two Corresponding Line Segments 173 Estimating Motion by Maximizing Overlap 175 4 2 2 Implementation Details 4 2 3 176 Reconstructing 3D Line Segments 4 2 4 179 4 2 5 Experimental Results 180 4 2 6 Discussions 192 4 3 Determining Epipolar Geometry of Three Views 194 4 3 1 Trifocal Constraints for Point Matches 194 4 3 2 Trifocal Constraints for Line Correspondences 199 4 3 3 Linear Estimation of K L and M Using Points and Lines 200 4 3 4 Determining Camera Projection Matrices 201 4 3 5 Image Transfer 203 4 4 Summary 204 5 REDEFINING STEREO MOTION AND OBJECT RECOGNITION VIA EPIPOLAR GEOMETRY 205 5 1 Conventional Approaches to Stereo Motion and Object Recognition 205 5 1 1 Stereo 205 5 1 2 Motion 206 5 1 3 Object Recognition 207 5 2 Correspondence in Stereo Motion and Object Recognition as 1D Search 209 5 2 1 Stereo Matching 209 xi Contents 5 2 2 Motion Correspondence and Segmentation 209 5 2 3 3D Object Recognition and Localization 210 Disparity and Spatial Disparity Space 210 5     Epipolar Geometry in Stereo, Motion and Object Recognition Gang Xu,Zhengyou Zhang,2013-03-09 Appendix 164 3 A 3 A 1 Approximate Estimation of Fundamental Matrix 164 3 A 2 Estimation of Affine Transformation 165 4 RECOVERY OF EPIPOLAR GEOMETRY FROM LINE SEGMENTS OR LINES 167 Line Segments or Straight Lines 168 4 1 4 2 Solving Motion Using Line Segments Between Two Views 173 4 2 1 Overlap of Two Corresponding Line Segments 173 Estimating Motion by Maximizing Overlap 175 4 2 2 Implementation Details 4 2 3 176 Reconstructing 3D Line Segments 4 2 4 179 4 2 5 Experimental Results 180 4 2 6 Discussions 192 4 3 Determining Epipolar Geometry of Three Views 194 4 3 1 Trifocal Constraints for Point Matches 194 4 3 2 Trifocal Constraints for Line Correspondences 199 4 3 3 Linear Estimation of K L and M Using Points and Lines 200 4 3 4 Determining Camera Projection Matrices 201 4 3 5 Image Transfer 203 4 4 Summary 204 5 REDEFINING STEREO MOTION AND OBJECT RECOGNITION VIA EPIPOLAR GEOMETRY 205 5 1 Conventional Approaches to Stereo Motion and Object Recognition 205 5 1 1 Stereo 205 5 1 2 Motion 206 5 1 3 Object Recognition 207 5 2 Correspondence in Stereo Motion and Object Recognition as 1D Search 209 5 2 1 Stereo Matching 209 xi Contents 5 2 2 Motion Correspondence and Segmentation 209 5 2 3 3D Object Recognition and Localization 210 Disparity and Spatial Disparity Space 210 5     *Computer Analysis of Images and Patterns* Wladyslaw Skarbek,2003-06-30 Computer analysis of images and patterns is a scientific field of longstanding tradition with roots in the early years of the computer era when electronic brains inspired scientists Moreover the design of vision machines is a part of humanity's dream of the artificial person I remember the 2nd CAIP held in Wismar in 1987 Lectures were read in German

English and Russian and proceedings were also only partially written in English The conference took place under a different political system and proved that ideas are independent of political walls A few years later the Berlin Wall collapsed and Professors Sommer and Klette proposed a new formula for the CAIP let it be held in Central and Eastern Europe every second year There was a sense of solidarity with scientific communities in those countries that found themselves in a state of transition to a new economy A well implemented idea resulted in a chain of successful events in Dresden 1991 Budapest 1993 Prague 1995 Kiel 1997 and Ljubljana 1999 This year the conference was welcomed at Warsaw There are three invited lectures and about 90 contributions written by more than 200 authors from 27 countries Besides Poland 60 authors the largest representation comes from France 23 followed by England 16 Czech Republic 11 Spain 10 Germany 9 and Belarus 9 Regrettably in spite of free registration fees and free accommodation for authors from former Soviet Union countries we received only one accepted paper from Russia

Biometric Identification Technologies Based on Modern Data Mining Methods Stepan Bilan, Mohamed Elhoseny, D. Jude Hemanth, 2020-12-03 This book emphasizes recent advances in the creation of biometric identification systems for various applications in the field of human activity The book displays the problems that arise in modern systems of biometric identification as well as the level of development and prospects for the introduction of biometric technologies The authors classify biometric technologies into two groups distinguished according to the type of biometric characteristics used The first group uses static biometric parameters fingerprints hand geometry retina pattern vein pattern on the finger etc The second group uses dynamic parameters for identification the dynamics of the reproduction of a signature or a handwritten keyword voice gait dynamics of work on the keyboard etc The directions of building information systems that use automatic personality identification based on the analysis of unique biometric characteristics of a person are discussed The book is intended for professionals working and conducting research in the field of intelligent information processing information security and robotics and in the field of real time identification systems The book contains examples and problems solutions throughout

*Pattern Recognition and Image Analysis* Joan Martí, 2007-05-31 Part of a two volume set this book constitutes the refereed proceedings of the Third Iberian Conference on Pattern Recognition and Image Analysis IbPRIA 2007 held in Girona Spain in June 2007 It covers pattern recognition human language technology special architectures and industrial applications motion analysis image analysis biomedical applications shape and texture analysis 3D and image coding and processing

**Digital Mammography** Nico Karssemeijer, Martin Thijssen, Jan Hendriks, Leon van Erning, 2012-12-06 In June 1998 the Fourth International Workshop on Digital Mammography was held in Nijmegen The Netherlands where it was hosted by the department of Radiology of the University Hospital Nijmegen This series of meetings was initiated at the 1993 SPIE Biomedical Image Processing Conference in San Jose USA where a number of sessions were entirely devoted to mammographic image analysis At very successful subsequent workshops held in York UK 1994 and Chicago USA 1996 the scope of the conference was broadened establishing a platform

for presentation and discussion of new developments in digital mammography Topics that are addressed at these meetings are computer aided diagnosis image processing detector development system design observer performance and clinical evaluation The goal is to bring researchers from universities breast cancer experts and engineers together to exchange information and present new scientific developments in this rapidly evolving field This book contains all the scientific papers and posters presented at the work shop in Nijmegen Contributions came from as many as 20 different countries and 190 participants attended the meeting At a technical exhibit companies demonstrated new products and work in progress Abstracts of all papers were reviewed by members of the scientific committee Many of the accepted papers had excellent quality but due to limited space not all of them could be included as full papers in these proceedings Papers that were rated high by the reviewers are included as long or short papers others appear as extended abstracts in the last chapter

**Panoramic Imaging** Fay Huang, Reinhard Klette, Karsten Scheibe, 2008-10-13 Panoramic imaging is a progressive application and research area This technology has applications in digital photography robotics film productions for panoramic screens architecture environmental studies remote sensing and GIS technology Applications demand different levels of accuracy for 3D documentation or visualizations This book describes two modern technologies for capturing high accuracy panoramic images and range data namely the use of sensor line cameras and laser range finders It provides mathematically accurate descriptions of the geometry of these sensing technologies and the necessary information required to apply them to 3D scene visualization or 3D representation The book is divided into three parts Part One contains a full introduction to panoramic cameras and laser range finders including a discussion of calibration to aid preparation of equipment ready for use Part Two explains the concept of stereo panoramic imaging looking at epipolar geometry spatial sampling image quality control and camera analysis and design Part Three looks at surface modelling and rendering based on panoramic input data starting with the basics and taking the reader through to more advanced techniques such as the optimization of surface meshes and data fusion There is also an accompanying website containing high resolution visual samples and animations illustrating techniques discussed in the text Panoramic Imaging is primarily aimed at researchers and students in engineering or computer science involved in using imaging technologies for 3D visualization or 3D scene reconstruction It is also of significant use as an advanced manual to practising engineers in panoramic imaging In brief the book is of value to all those interested in current developments in multimedia imaging technology

**Robotics, Vision and Control** Peter Corke, Witold Jachimczyk, Remo Pillat, 2023-05-15 This textbook provides a comprehensive but tutorial introduction to robotics computer vision and control It is written in a light but informative conversational style weaving text figures mathematics and lines of code into a cohesive narrative Over 1600 code examples show how complex problems can be decomposed and solved using just a few simple lines of code This edition is based on MATLAB and a number of MathWorks toolboxes These provide a set of supported software tools for addressing a broad range of applications in robotics

and computer vision These toolboxes enable the reader to easily bring the algorithmic concepts into practice and work with real non trivial problems For the beginning student the book makes the algorithms accessible the toolbox code can be read to gain understanding and the examples illustrate how it can be used The code can also be the starting point for new work for practitioners students or researchers by writing programs based on toolbox functions Two co authors from MathWorks have joined the writing team and bring deep knowledge of these MATLAB toolboxes and workflows

### **Image-Based Rendering**

Heung-Yeung Shum, Shing-Chow Chan, Sing Bing Kang, 2008-05-26 Image Based Rendering examines the theory practice and applications associated with image based rendering and modeling As leading researchers in the field the authors combine their unique experiences in computer graphics computer vision and signal processing to address the multidisciplinary nature of IBR research The topics covered vary from IBR basic concepts and representations on the theory side to signal processing and data compression on the practical side Several IBR systems built to date are examined Rather than focusing on 3D modeling aspects which have been extensively treated elsewhere in the vision literature the book focuses primarily on IBR One of the only titles devoted exclusively to IBR this book is intended for researchers professionals and general readers interested in the topics of computer graphics computer vision image process and video processing Advanced level students in EECS studying related disciplines will be able to seriously expand their knowledge about image based rendering

*Semantic Analysis and Understanding of Human Behavior in Video Streaming* Alberto Amato, Vincenzo Di Lecce, Vincenzo Piuri, 2012-09-18 Semantic Analysis and Understanding of Human Behaviour in Video Streaming investigates the semantic analysis of the human behaviour captured by video streaming and introduces both theoretical and technological points of view Video analysis based on the semantic content is in fact still an open issue for the computer vision research community especially when real time analysis of complex scenes is concerned This book explores an innovative original approach to human behaviour analysis and understanding by using the syntactical symbolic analysis of images and video streaming described by means of strings of symbols A symbol is associated to each area of the analyzed scene When a moving object enters an area the corresponding symbol is appended to the string describing the motion This approach allows for characterizing the motion of a moving object with a word composed by symbols By studying and classifying these words we can categorize and understand the various behaviours The main advantage of this approach lies in the simplicity of the scene and motion descriptions so that the behaviour analysis will have limited computational complexity due to the intrinsic nature both of the representations and the related operations used to manipulate them Besides the structure of the representations is well suited for possible parallel processing thus allowing for speeding up the analysis when appropriate hardware architectures are used A new methodology for design systems for hierarchical high semantic level analysis of video streaming in narrow domains is also proposed Guidelines to design your own system are provided in this book Designed for practitioners computer scientists and engineers working within the fields of human computer interaction surveillance image

processing and computer vision this book can also be used as secondary text book for advanced level students in computer science and engineering

Ridges in Image and Data Analysis D. Eberly, 2012-12-06 The concept of ridges has appeared numerous times in the image processing literature. Sometimes the term is used in an intuitive sense. Other times a concrete definition is provided. In almost all cases the concept is used for very specific applications. When analyzing images or data sets it is very natural for a scientist to measure critical behavior by considering maxima or minima of the data. These critical points are relatively easy to compute. Numerical packages always provide support for root finding or optimization whether it be through bisection, Newton's method, conjugate gradient method or other standard methods. It has not been natural for scientists to consider critical behavior in a higher order sense. The concept of ridge as a manifold of critical points is a natural extension of the concept of local maximum as an isolated critical point. However, almost no attention has been given to formalizing the concept. There is a need for a formal development. There is a need for understanding the computation issues that arise in the implementations. The purpose of this book is to address both needs by providing a formal mathematical foundation and a computational framework for ridges. The intended audience for this book includes anyone interested in exploring the usefulness of ridges in data analysis.

*Computer Vision - ECCV'98* Hans Burkhardt, Bernd Neumann, 1998-05-26 This two volume set constitutes the refereed proceedings of the 5th European Conference on Computer Vision ECCV 98 held in Freiburg, Germany, in June 1998. The 42 revised full papers and 70 revised posters presented were carefully selected from a total of 223 papers submitted. The papers are organized in sections on multiple view geometry, stereo vision and calibration geometry and invariances, structure from motion, colour and indexing, grouping and segmentation, tracking, condensation matching and registration, image sequences and video, shape and shading, motion and flow, medical imaging, appearance and recognition, robotics and active vision, and motion segmentation.

*Noblesse Workshop on Non-Linear Model Based Image Analysis* Stephen Marshall, Neal R. Harvey, Druti Shah, 2012-12-06 This book contains papers presented at the Noblesse Workshop on Non-linear model based image analysis held in Glasgow, 1-3 July 1998. Current models have mainly been developed for image coding purposes. They are rather simple and far away from being optimal and do not contribute to more complex tasks like those needed in image databases. This book meets the challenging tasks in multimedia applications by discussing new sophisticated model based schemes for a high level description of images and image sequences. Novel results are covered in the papers presented in this book, opening new potential fields of application like the support for building databases in multimedia applications, image archiving and image sequence coding, including such topics as 3D Image Models, Image Video Restoration, Segmentation and Object Oriented Coding, Colour Image Processing, Database Retrieval, Image Models, Video Pre and Post processing.

Front-End Vision and Multi-Scale Image Analysis Bart M. Haer, Romeny, 2008-10-24 Many approaches have been proposed to solve the problem of finding the optic flow field of an image sequence. Three major classes of optic flow computation techniques can be discriminated: see for a good

overview Beauchemin and Barron [Beauchemin1995] gradient based or differential methods phase based or frequency domain methods correlation based or area methods feature point or sparse data tracking methods In this chapter we compute the optic flow as a dense optic flow field with a multi scale differential method The method originally proposed by Florack and Nielsen [Florack1998a] is known as the Multiscale Optic Flow Constrain Equation MOFCE This is a scale space version of the well known computer vision implementation of the optic flow constraint equation as originally proposed by Horn and Schunck [Horn1981] This scale space variation as usual consists of the introduction of the aperture of the observation in the process The application to stereo has been described by Maas et al [Maas 1995a, Maas 1996a] Of course difficulties arise when structure emerges or disappears such as with occlusion cloud formation etc Then knowledge is needed about the processes and objects involved In this chapter we focus on the scale space approach to the local measurement of optic flow as we may expect the visual front end to do

17.2 Motion detection with pairs of receptive fields As a biologically motivated start we begin with discussing some neurophysiological findings in the visual system with respect to motion detection

Advances in Visual Computing Richard Boyle, Darko Koracin, Bahram Parvin, 2005-11-29 It is with great pleasure that I welcome you to Lake Tahoe for the 2005 International Symposium on Visual Computing ISVC ISVC provides a common umbrella for the four main areas of visual computing vision graphics visualization and virtual reality The goal of ISVC is to provide a common forum for researchers scientists engineers and practitioners throughout the world to present their latest research findings ideas developments and applications in the broader area of visual computing The program consists of six oral sessions two poster sessions seven special tracks four keynote presentations and one invited presentation The response to the call for papers for the general ISVC 2005 sessions was very good We received over 110 submissions from which we accepted 33 papers for oral presentation and 26 papers for poster presentation Special track papers were solicited separately through the organizing and program committees of each track A total of 32 papers were accepted for inclusion in the special tracks All papers were reviewed with an emphasis on their potential to contribute to the state of the art in the field Selection criteria included accuracy and originality of ideas clarity and significance of results and presentation quality The review process was quite rigorous involving two or three independent double blind reviews followed by a one week discussion period During the discussion period we tried to correct anomalies and errors that might have existed in the initial reviews Despite our efforts we recognize that some papers worthy of inclusion may not have been included in the program We offer our sincere apologies to authors whose contributions might have been overlooked

I wish to thank everybody who submitted their work to ISVC 2005 for review

**Machine Vision and Navigation** Oleg Sergiyenko, Wendy Flores-Fuentes, Paolo Mercorelli, 2019-09-30 This book presents a variety of perspectives on vision based applications These contributions are focused on optoelectronic sensors 3D Discusses applications such as daily use devices including robotics detection tracking and stereoscopic vision systems pose estimation avoidance of objects control and data



exchange for navigation and aerial imagery processing Includes research contributions in scientific industrial and civil applications     *Handbook of Computer Vision and Applications: Signal processing and pattern recognition* ,1999 CD ROM files contain complete text of all three print vols in the Adobe Acrobat portable document file format PDF as well as hyperlinks to figures tables etc and between the index and the text Also included are hyperlinks to movies interactive 3 D models demonstration software and additional reference and image materials not contained in the print version

*Image-Based 3D Reconstruction of Dynamic Objects Using Instance-Aware Multibody Structure from Motion* Bullinger, Sebastian,2020-08-26 This work proposes a Multibody Structure from Motion MSfM algorithm for moving object reconstruction that incorporates instance aware semantic segmentation and multiple view geometry methods The MSfM pipeline tracks two dimensional object shapes on pixel level to determine object specific feature correspondences in order to reconstruct 3D object shapes as well as 3D object motion trajectories Publicaciones de Arquitectura y Arte     Computer Vision and Applications Bernd Jahne,2000-05-24 Based on the highly successful 3 volume reference Handbook of Computer Vision and Applications this concise edition covers in a single volume the entire spectrum of computer vision ranging from the imaging process to high end algorithms and applications This book consists of three parts including an application gallery Bridges the gap between theory and practical applications Covers modern concepts in computer vision as well as modern developments in imaging sensor technology Presents a unique interdisciplinary approach covering different areas of modern science     **Machine Learning in Computer Vision** Nicu Sebe,2005-06-03 The goal of this book is to address the use of several important machine learning techniques into computer vision applications An innovative combination of computer vision and machine learning techniques has the promise of advancing the field of computer vision which contributes to better understanding of complex real world applications The effective usage of machine learning technology in real world computer vision problems requires understanding the domain of application abstraction of a learning problem from a given computer vision task and the selection of appropriate representations for the learnable input and learned internal entities of the system In this book we address all these important aspects from a new perspective that the key element in the current computer revolution is the use of machine learning to capture the variations in visual appearance rather than having the designer of the model accomplish this As a bonus models learned from large datasets are likely to be more robust and more realistic than the brittle all design models

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