

# Lab Problem - Dynamic Analysis of an Epicyclic Gear Train

## Problem Description:

Planetary or epicyclic Gear Train is a commonly-used gear drive. An epicyclic gear train can consist of two gears mounted so that the centre of one gear revolves around the centre of the other. A carrier connects the centres of the two gears and rotates to carry one gear, called the planet gear, around the other, called the sun gear. A simple EGT can have two-DOF, arm angular velocity and gear angular velocity and the velocity of the gear can be calculated using the epicyclic gear equation  $\omega_{\text{gear}} = \omega_{\text{arm}} + \omega_{\text{gear/arm}}$ .

In this lab problem, you are required to perform a motion analysis of a simple EGT to determine the absolute output angular velocity of the ring gear, as shown in Figure 1. The given parameters are: Sun gear (2)  $N_2 = 36$  teeth (external gear); Planet gear (3)  $N_3 = 22$  teeth (external gear); Ring (annulus) gear (4)  $N_4 = 80$  teeth (internal gear); Input to arm, 291 rpm CW; Input to sun, 191 rpm CW.

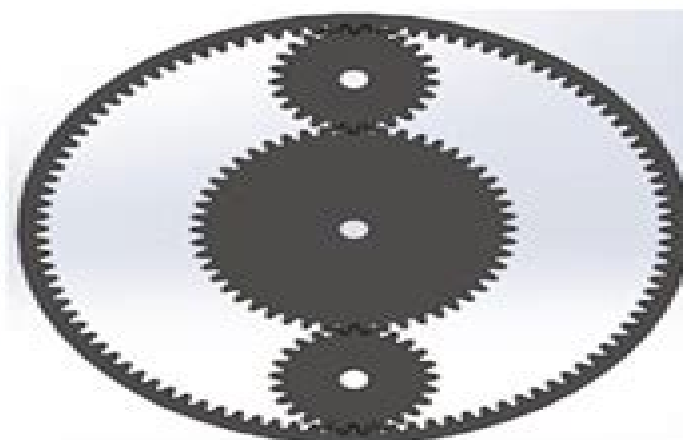
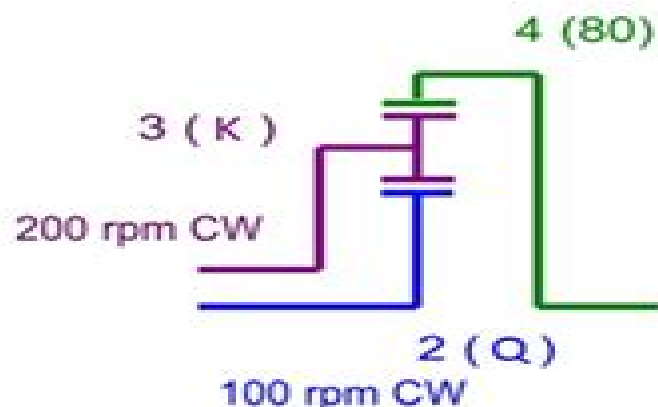


Figure 1 Motion Analysis of a moving conveyer and a block

You need to get the analytical solution using the epicyclic gear equation of gear velocity for validation. You are required to create a CAD model of the EGT. You can easily create the gears using SolidWorks Toolbox considering appropriate numbers of teeth each gear may have. Appropriate shaft and **arm should be created** if necessary.

## Analytic Results of Motion Analysis of the EGT

You need to **apply the Tabular Method** to solve this problem and show the problem-solving procedure in a step by step manner.

# Epicyclic Gear Train Problems And Solutions

**John J. Uicker, Bahram Ravani, Pradip N. Sheth**



## **Epicyclic Gear Train Problems And Solutions:**

**A Text Book of Theory of Machines** J. S. Brar, R. K. Bansal, 2004      The Theory Of Machines Through Solved Problems J. S. Rao, 2007

The Theory Of Machines Or Mechanism And Machine Theory Is A Basic Subject Taught In Engineering Schools To Mechanical Engineering Students This Subject Lays The Foundation On Which Mechanical Engineering Design And Practice Rests With It Is Also A Subject Taught When The Students Have Just Entered Engineering Discipline And Are Yet To Formulate Basics Of Mechanical Engineering This Subject Needs A Lot Of Practice In Solving Engineering Problems And There Is Currently No Good Book Explaining The Subject Through Solved Problems This Book Is Written To Fill Such A Void And Help The Students Preparing For Examinations It Contains In All 336 Solved Problems Several Illustrations And 138 Additional Problems For Practice Basic Theory And Background Is Presented Though It Is Not Like A Full Fledged Text Book In That Sense This Book Contains 20 Chapters The First One Giving A Historical Background On The Subject The Second Chapter Deals With Planar Mechanisms Explaining Basic Concepts Of Machines Kinematic Analysis Is Given In Chapter 3 With Graphical As Well As Analytical Tools The Synthesis Of Mechanisms Is Given In Chapter 4 Additional Mechanisms And Coupler Curve Theory Is Presented In Chapter 5 Chapter 6 Discusses Various Kinds Of Cams Their Analysis And Design Spur Gears Helical Gears Worm Gears And Bevel Gears And Gear Trains Are Extensively Dealt With In Chapters 7 To 9 Hydrodynamic Thrust And Journal Bearings Long And Short Bearings Are Considered In Chapter 10 Static Forces Inertia Forces And A Combined Force Analysis Of Machines Is Considered In Chapters 11 To 13 The Turning Moment And Flywheel Design Is Given In Chapter 14 Chapters 15 And 16 Deal With Balancing Of Rotating Parts Reciprocating Parts And Four Bar Linkages Force Analysis Of Gears And Cams Is Dealt With In Chapter 17 Chapter 18 Is Concerned With Mechanisms Used In Control Viz Governors And Gyroscopes Chapters 19 And 20 Introduce Basic Concepts Of Machine Vibrations And Critical Speeds Of Machinery A Special Feature Of This Book Is The Availability Of Three Computer Aided Learning Packages For Planar Mechanisms Their Analysis And Animation For Analysis Of Cams With Different Followers And Dynamics Of Reciprocating Machines Balancing And Flywheel Analysis

**Gear Geometry and Applied Theory** Faydor L. Litvin, Alfonso Fuentes, 2004-09-06 This revised expanded edition covers the theory design geometry and manufacture of all types of gears and gear drives This is an invaluable reference for designers theoreticians students and manufacturers This edition includes advances in gear theory gear manufacturing and computer simulation Among the new topics are 1 New geometry for modified spur and helical gears face gear drives and cycloidal pumps 2 New design approaches for one stage planetary gear trains and spiral bevel gear drives 3 An enhanced approach for stress analysis of gear drives with FEM 4 New methods of grinding face gear drives generating double crowned pinions and improved helical gear shaving 5 Broad application of simulation of meshing and TCA 6 New theories on the simulation of meshing for multi body systems detection of cases wherein the contact line on generating surfaces may have its own

envelope and detection and avoidance of singularities of generated surfaces      **Machine Design Problem Solver** ,1988

**Planetary Gear Trains** Kiril Arnaudov,Dimitar Petkov Karaivanov,2019-03-27 This book provides comprehensive information for various planetary gear trains with practical applications and comprehensive references to technical articles In the text s chapters readers can find all the information needed for various types of gear trains with illustrations and examples The authors help gear designers to creatively understand the design of gears as well as master the mechanical calculations needed Planetary Gear Trains is the most comprehensive and up to date work available in this key technical area The book reflects not only teaching but also the practical experience of the authors It was developed under the motto From practice to practice      **Advanced Engineering Optimization Through Intelligent Techniques** Ravipudi Venkata

Rao,Jan Taler,2023-04-07 This book comprises peer reviewed papers presented at the International Conference on Advanced Engineering Optimization Through Intelligent Techniques AEOTIT 2022 The book combines contributions from academics and industry professionals and covers advanced optimization techniques across all major engineering disciplines like mechanical manufacturing civil automobile electrical chemical computer and electronics engineering The book discusses different optimization techniques and algorithms such as genetic algorithm non dominated sorting genetic algorithm II and III differential search particle swarm optimization fruit fly algorithm cuckoo search teaching learning based optimization algorithm grey wolf optimization Jaya algorithm Rao algorithms and many other latest meta heuristic techniques and their applications Various multi attribute decision making methods such as AHP TOPSIS ELECTRE PROMETHEE DEMATEL R method fuzzy logic and their applications are also discussed This book serves as a valuable reference for students researchers and practitioners and helps them in solving a wide range of optimization problems      **VIBRATION AND**

**NOISE REDUCTION IN PLANETARY GEAR TRAIN BY PHASING** Ashutosh Mokate,2016-03-10 Gears are essential parts of many precision power transmitting machines such as automobiles The major functions of a gearbox are to transform speed and torque in a given ratio and to change the axis of rotation Planetary gears yield several advantages over conventional parallel shaft gear systems They produce high speed reductions in compact spaces a greater load sharing a higher torque to weight ratio diminished bearing loads and reduced noise and vibration They are used in automobiles helicopters aircraft engines heavy machinery and a variety of other applications Despite their advantages the noise induced by the vibration of planetary gear systems remains a key concern Planetary gears have received considerably less research attention than single mesh gear pairs There is a particular scarcity of analysis of two planetary gear systems and their dynamic response Hence this book focuses on the study of two PGTs with different phasing angular positions while every individual set remains unchanged      **Kinematics, Dynamics, and Design of Machinery** Kenneth J. Waldron,Gary L. Kinzel,Sunil K.

Agrawal,2016-09-20 Kinematics Dynamics and Design of Machinery Third Edition presents a fresh approach to kinematic design and analysis and is an ideal textbook for senior undergraduates and graduates in mechanical automotive and

production engineering Presents the traditional approach to the design and analysis of kinematic problems and shows how GCP can be used to solve the same problems more simply Provides a new and simpler approach to cam design Includes an increased number of exercise problems Accompanied by a website hosting a solutions manual teaching slides and MATLAB programs

**Mechanical Design** P.R.N. Childs, 2003-12-04 This book introduces the subject of total design and introduces the design and selection of various common mechanical engineering components and machine elements These provide building blocks with which the engineer can practice his or her art The approach adopted for defining design follows that developed by the SEED Sharing Experience in Engineering Design programme where design is viewed as the total activity necessary to provide a product or process to meet a market need Within this framework the book concentrates on developing detailed mechanical design skills in the areas of bearings shafts gears seals belt and chain drives clutches and brakes springs and fasteners Where standard components are available from manufacturers the steps necessary for their specification and selection are developed The framework used within the text has been to provide descriptive and illustrative information to introduce principles and individual components and to expose the reader to the detailed methods and calculations necessary to specify and design or select a component To provide the reader with sufficient information to develop the necessary skills to repeat calculations and selection processes detailed examples and worked solutions are supplied throughout the text This book is principally a Year Level 1 and 2 undergraduate text Pre requisite skills include some year one undergraduate mathematics fluid mechanics and heat transfer principles of materials statics and dynamics However as the subjects are introduced in a descriptive and illustrative format and as full worked solutions are provided it is possible for readers without this formal level of education to benefit from this book The text is specifically aimed at automotive and mechanical engineering degree programmes and would be of value for modules in design mechanical engineering design design and manufacture design studies automotive power train and transmission and tribology as well as modules and project work incorporating a design element requiring knowledge about any of the content described The aims and objectives described are achieved by a short introductory chapters on total design mechanical engineering and machine elements followed by ten chapters on machine elements covering bearings shafts gears seals chain and belt drives clutches and brakes springs fasteners and miscellaneous mechanisms Chapters 14 and 15 introduce casings and enclosures and sensors and actuators key features of most forms of mechanical technology The subject of tolerancing from a component to a process level is introduced in Chapter 16 The last chapter serves to present an integrated design using the detailed design aspects covered within the book The design methods where appropriate are developed to national and international standards e.g. ANSI ASME AGMA BSI DIN ISO The first edition of this text introduced a variety of machine elements as building blocks with which design of mechanical devices can be undertaken The approach adopted of introducing and explaining the aspects of technology by means of text photographs diagrams and step by step procedures has been maintained A number of important

machine elements have been included in the new edition fasteners springs sensors and actuators They are included here Chapters on total design the scope of mechanical engineering and machine elements have been completely revised and updated New chapters are included on casings and enclosures and miscellaneous mechanisms and the final chapter has been rewritten to provide an integrated approach Multiple worked examples and completed solutions are included *Matrix Methods Applied to Engineering Rigid Body Mechanics* T. Crouch, 2016-07-29 Explains the use of matrixes and their application to the solution of rigid body mechanics problems Text is supported by chapters of worked examples **Dynamic Decoupling of Robot Manipulators** Vigen Arakelian, 2018-02-20 This book presents the latest results in the field of dynamic decoupling of robot manipulators obtained in France Russia China and Austria Manipulator dynamics can be highly coupled and nonlinear The complicated dynamics result from varying inertia interactions between the different joints and nonlinear forces such as Coriolis and centrifugal forces The dynamic decoupling of robot manipulators allows one to obtain a linear system i e single input and single output system with constant parameters This simplifies the optimal control and accumulation of energy in manipulators There are two ways to create the dynamically decoupled manipulators via optimal mechanical design or control This work emphasises mechatronic solutions These will certainly improve the known design concepts permitting the dynamic decoupling of serial manipulators with a relatively small increase in total mass of the moving links taking into account the changing payload For the first time such an approach has been applied on serial manipulators Also of great interest is the dynamic decoupling control of parallel manipulators Firstly the dynamic model of redundant multi axial vibration table with load has been established and secondly its dynamic coupling characteristics have been analyzed The discussed methods and applications of dynamic decoupling of robot manipulators are illustrated via CAD simulations and experimental tests **TNPSC-Tamilnadu Combined Technical Services Exam-Technical Executive (Mechanical) Exam-Mechanical Engineering Subject Practice Sets** Chandresh Agrawal, 2025-01-22 SGN The TNPSC Tamilnadu Combined Technical Services Exam Technical Executive Mechanical Exam Mechanical Engineering Subject Practice Sets Covers Objective Questions With Answers [TNPSC Exam PDF-Tamilnadu Combined Technical Services Exam-Manager \(Mechanical\) Exam-Mechanical Engineering Subject Practice Sets eBook](#) Chandresh Agrawal, Nandini Books, 2025-01-20 SGN The TNPSC Exam PDF Tamilnadu Combined Technical Services Exam Manager Mechanical Exam Mechanical Engineering Subject Practice Sets eBook Covers Objective Questions With Answers **Rotating Machinery, Optical Methods & Scanning LDV Methods, Volume 6** Dario Di Maio, Javad Baqersad, 2022-07-05 Rotating Machinery Optical Methods Scanning LDV Methods Volume 6 Proceedings of the 40th IMAC A Conference and Exposition on Structural Dynamics 2022 the sixth volume of nine from the Conference brings together contributions to this important area of research and engineering The collection presents early findings and case studies on fundamental and applied aspects of Structural Health Monitoring including papers on Novel Techniques Optical Methods Scanning LDV Methods Photogrammetry DIC

Rotating Machinery      Fundamentals of Machine Design: Ajeet Singh, 2017-09-15 Written in a user friendly manner the text provides detailed discussions on design principles of belts pulleys ropes chain drives and gear boxes The text being a follow up to the first volume discusses properties types advantages and selection aspects of belt drives flat belt pulleys grooved pulleys and rope drives It then explains construction aspects classification properties and the design procedure of important bearings including hydrodynamic and rolling bearings It goes on to discuss several types of I C engine parts including cylinder piston connecting rod crank shaft valve gears flywheels clutches and brakes Advantages and applications of worm and worm wheel drives and pressure vessels are also included      *Scientific and Technical Aerospace Reports* ,1994

**Epicyclic Gearing** Chandrasekaran G, 2025-05-08 This book provides a broad introduction to the optimization techniques used in the design and manufacturing of epicyclic gearing A wide variety of optimization techniques are covered with a strong focus on practical application The formulation of the underlying mathematical models and the algorithms for solving them are explained which are then applied to solve real world problems in epicyclic gearing Figures and charts are provided to convey the intuition behind the various approaches Each chapter includes a detailed case study based on a real world application of epicyclic gearing The case studies highlight the realities and challenges in the design optimization of epicyclic gearing systems illustrate the application of optimization techniques in a real world context compare different optimization techniques in terms of performance ease of use etc and identify the areas of future work Suitable for gear professionals and researchers alike the book will be of interest to those in the fields of mechanical engineering statistics computer science aerospace automotive engineering and operations research      **Applied Mechanics Reviews** ,1974

*Engineering; an Illustrated Weekly Journal* ,1950      **Matrix Methods in the Design Analysis of Mechanisms and Multibody Systems** John J. Uicker, Bahram Ravani, Pradip N. Sheth, 2013-04-15 This book is an integrated approach to kinematic and dynamic analysis The matrix techniques presented are general and fully applicable to two or three dimensional systems They lend themselves to programming and digital computation and can act as the basis of a usable tool for designers Techniques have broad applicability to the design analysis of all multibody mechanical systems The more powerful and more flexible the approach and the less specialisation and reprogramming required for each application the better The matrix methods presented have been developed using these ideas as primary goals Matrix methods can be applied by hand to such problems as the slider crank mechanism but this is not the intent of this text and often the rigor required for such an attempt becomes quite burdensome in comparison with other techniques The matrix methods have been extensively tested both in the classroom and in the world of engineering industry

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