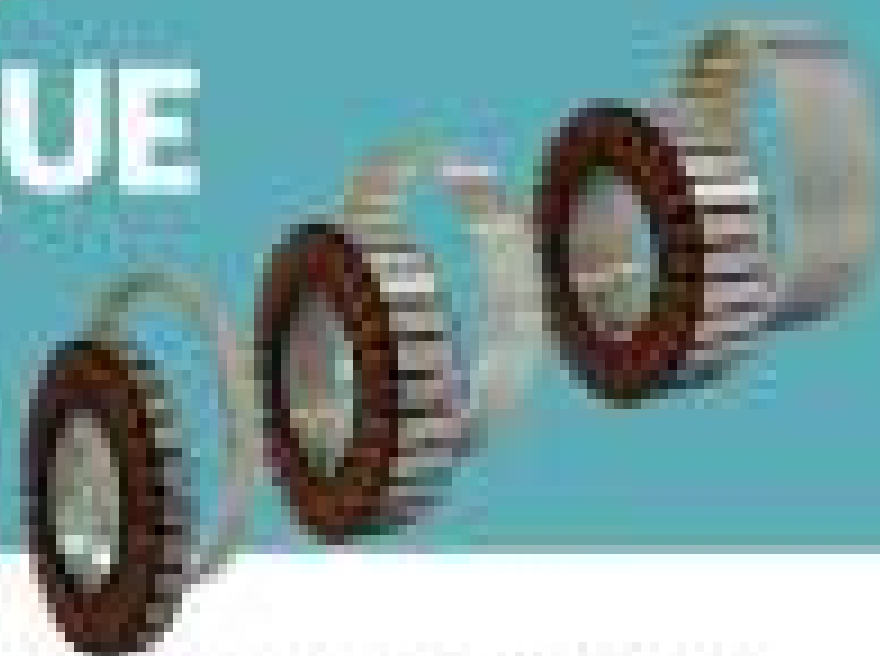


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Intelligent Robotics and Applications Huayong Yang, Honghai Liu, Jun Zou, Zhouping Yin, Lianqing Liu, Geng Yang, Xiaoping Ouyang, Zhiyong Wang, 2023-10-15 The 9 volume set LNAI 14267 14275 constitutes the proceedings of the 16th International Conference on Intelligent Robotics and Applications ICIRA 2023 which took place in Hangzhou China during July 5 7 2023 The 413 papers included in these proceedings were carefully reviewed and selected from 630 submissions They were organized in topical sections as follows Part I Human Centric Technologies for Seamless Human Robot Collaboration Multimodal Collaborative Perception and Fusion Intelligent Robot Perception in Unknown Environments Vision Based Human Robot Interaction and Application Part II Vision Based Human Robot Interaction and Application Reliable AI on Machine Human Reactions Wearable Sensors and Robots Wearable Robots for Assistance Augmentation and Rehabilitation of Human Movements Perception and Manipulation of Dexterous Hand for Humanoid Robot Part III Perception and Manipulation of Dexterous Hand for Humanoid Robot Medical Imaging for Biomedical Robotics Advanced Underwater Robot Technologies Innovative Design and Performance Evaluation of Robot Mechanisms Evaluation of Wearable Robots for Assistance and Rehabilitation 3D Printing Soft Robots Part IV 3D Printing Soft Robots Dielectric Elastomer Actuators for Soft Robotics Human like Locomotion and Manipulation Pattern Recognition and Machine Learning for Smart Robots Part V Pattern Recognition and Machine Learning for Smart Robots Robotic Tactile Sensation Perception and Applications Advanced Sensing and Control Technology for Human Robot Interaction Knowledge Based Robot Decision Making and Manipulation Design and Control of Legged Robots Part VI Design and Control of Legged Robots Robots in Tunnelling and Underground Space Robotic Machining of Complex Components Clinically Oriented Design in Robotic Surgery and Rehabilitation Visual and Visual Tactile Perception for Robotics Part VII Visual and Visual Tactile Perception for Robotics Perception Interaction and Control of Wearable Robots Marine Robotics and Applications Multi Robot Systems for Real World Applications Physical and Neurological Human Robot Interaction Part VIII Physical and Neurological Human Robot Interaction Advanced Motion Control Technologies for Mobile Robots Intelligent Inspection Robotics Robotics in Sustainable

Manufacturing for Carbon Neutrality Innovative Design and Performance Evaluation of Robot Mechanisms Part IX Innovative Design and Performance Evaluation of Robot Mechanisms Cutting Edge Research in Robotics *Advances in Mechanical Systems Dynamics* Alberto Doria, Giovanni Boschetti, Matteo Massaro, 2020-02-13 Modern dynamics was established many centuries ago by Galileo and Newton before the beginning of the industrial era Presently we are in the presence of the fourth industrial revolution and mechanical systems are increasingly being integrated with electronic electrical and fluidic systems This trend is present not only in the industrial environment which will soon be characterized by the cyber physical systems of industry 4 0 but also in other environments like mobility health and bio engineering food and natural resources safety and sustainable living In this context purely mechanical systems with quasi static behavior will become less common and the state of the art will soon be represented by integrated mechanical systems which need accurate dynamic models to predict their behavior Therefore mechanical system dynamics are going to play an increasingly central role Significant research efforts are needed to improve the identification of the mechanical properties of systems in order to develop models that take non linearity into account and to develop efficient simulation tools This Special Issue aims at disseminating the latest research achievements findings and ideas in mechanical systems dynamics with particular emphasis on applications that are strongly integrated with other systems and require a multi physical approach **Electric Drives and Electromechanical Systems** Richard Crowder, 2019-10-19 Electric Drives and Electromechanical Devices Applications and Control Second Edition presents a unified approach to the design and application of modern drive system It explores problems involved in assembling complete modern electric drive systems involving mechanical electrical and electronic elements This book provides a global overview of design specification applications important design information and methodologies This new edition has been restructured to present a seamless logical discussion on a wide range of topical problems relating to the design and specification of the complete motor drive system It is organised to establish immediate solutions to specific application problem Subsidiary issues that have a considerable impact on the overall performance and reliability including environmental protection and costs energy efficiency and cyber security are also considered Presents a comprehensive consideration of electromechanical systems with insights into the complete drive system including required sensors and mechanical components Features in depth discussion of control schemes particularly focusing on practical operation Includes extensive references to modern application domains and real world case studies such as electric vehicles Considers the cyber aspects of drives including networking and security **The 29th Aerospace Mechanisms Symposium** William C. Schneider, 1995 **Mechanical Design and Manufacturing of Electric Motors** Wei Tong, 2022-05-19 This Second Edition of Mechanical Design and Manufacturing of Electric Motors provides in depth knowledge of design methods and developments of electric motors in the context of rapid increases in energy consumption and emphasis on environmental protection alongside new technology in 3D printing robots nanotechnology and digital techniques and the challenges these

pose to the motor industry From motor classification and design of motor components to model setup and material and bearing selections this comprehensive text covers the fundamentals of practical design and design related issues modeling and simulation engineering analysis manufacturing processes testing procedures and performance characteristics of electric motors today This Second Edition adds three brand new chapters on motor breaks motor sensors and power transmission and gearing systems Using a practical approach with a focus on innovative design and applications the book contains a thorough discussion of major components and subsystems such as rotors shafts stators and frames alongside various cooling techniques including natural and forced air direct and indirect liquid phase change and other newly emerged innovative cooling methods It also analyzes the calculation of motor power losses motor vibration and acoustic noise issues and presents engineering analysis methods and case study results While suitable for motor engineers designers manufacturers and end users the book will also be of interest to maintenance personnel undergraduate and graduate students and academic researchers

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,2005 *Mechanical Design of Electric Motors* Wei Tong,2014-04-28 Rapid increases in energy consumption and emphasis on environmental protection have posed challenges for the motor industry as has the design and manufacture of highly efficient reliable cost effective energy saving quiet precisely controlled and long lasting electric motors Suitable for motor designers engineers and manufacturers as well *Power Energy and Secure Smart Technologies* Thanikanti Sudhakar Babu,Mallala Balasubbareddy,Subramaniam M,Nnamdi Nwulu,Vigna Kumaran Ramachandaramurthy,Renu Sharma,2025-07-16 This Book of Proceedings presents the collective research and insights shared at the conference on Power Energy and Secure Smart Technologies The event brings together leading minds from academia industry and research to explore innovations and address challenges in modern power systems sustainable energy solutions and secure smart technologies The papers compiled here reflect the latest developments case studies and forward looking ideas that contribute to the evolving landscape of intelligent and resilient energy systems We trust this volume will serve as a valuable resource for researchers professionals and students committed to advancing technology for a sustainable and secure energy future

Military Standard United States. Dept. of Defense, **An Active Nutation Damper for Spacecraft** Richard A. Abercrombie, Thomas W. Flatley, 1977 **NASA Technical Paper**, 1977 *Disaster Robotics* Satoshi Tadokoro, 2019-01-20 This book introduces readers to the latest findings on disaster robotics It is based on the ImPACT Tough Robotics Challenge a national project spearheaded by the Japan Cabinet Office that focuses on developing robotics technologies to aid in disaster response recovery and preparedness It presents six subprojects that involve robot platforms and several component technologies used in conjunction with robots cyber rescue canines which are digitally empowered rescue dogs serpent like robots for searching debris serpent like robots for plant infrastructure inspection UAVs for gathering information on large areas struck by disaster legged robots for plant infrastructure inspection in risky places and construction robots for recovery tasks that require both power and precision The book offers a valuable source of information for researchers engineers and practitioners in safety security and rescue robotics disaster robotics and plant and infrastructure maintenance It will also appeal to a wider demographic including students and academics as it highlights application scenarios and the total concept for each robot in various scientific and technical contexts In addition to a wealth of figures and photos that explain these robots and systems as well as experimental data the book includes a comprehensive list of published papers from this project for readers to refer to Lastly an external website offers video footage and updated information from the International Rescue System Institute [Engineering Materials and Design](#), 1987 **2nd International Conference on Electrical Variable-Speed Drives, 25-27 September 1979** Institution of Electrical Engineers. Power Division, 1979 Cover title Electrical variable speed drives **The International Handbook of Space Technology** Malcolm Macdonald, Viorel Badescu, 2014-07-08 This comprehensive handbook provides an overview of space technology and a holistic understanding of the system of systems that is a modern spacecraft With a foreword by Elon Musk CEO and CTO of SpaceX and contributions from globally leading agency experts from NASA ESA JAXA and CNES as well as European and North American academics and industrialists this handbook as well as giving an interdisciplinary overview offers through individual self contained chapters more detailed understanding of specific fields ranging through Launch systems structures power thermal communications propulsion and software to entry descent and landing ground segment robotics and data systems to technology management legal and regulatory issues and project management This handbook is an equally invaluable asset to those on a career path towards the space industry as it is to those already within the industry *Control Engineering*, 1978 Instrumentation and automatic control systems

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